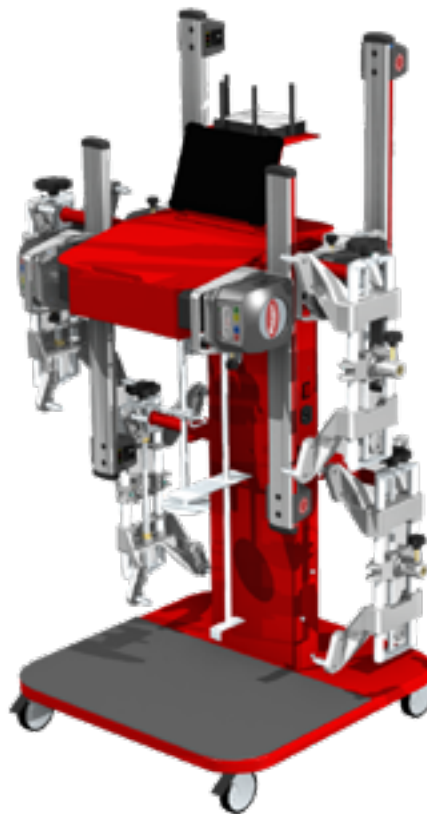




RWA1065

INSTRUCTION MANUAL



COMPOSITION

48 pages (including cover pages)

46 numbered pages

- **For any further information please contact your local dealer. Contact info are on the last page.**

IMPORTANT Any damage caused by failure to follow the instructions in this manual or improper machine use shall relieve the manufacturer of all liability.

SYMBOLS USED IN THE MANUAL

	SYMBOLS
	FORBIDDEN!
	Mandatory! Operations or jobs to be performed compulsorily
	Hazard! Be especially careful

TABLE OF CONTENTS

1	WARNINGS	6
1.1	Preliminary safety information	6
2	INTENDED USE	7
3	TRAINING OF THE PERSONNEL	7
3.1	General preventive measures	7
4	COMPOSITION OF THE EQUIPMENT	8
4.1	Clamp compartment (optional)	9
4.1.1	STDA156 (wall-mounted panels)	9
4.1.2	STDA155 (clamp trolley)	9
4.1.3	STDA157 (wall hooks)	9
4.2	Measuring ranges and accuracy	10
4.3	Overall dimensions	10
4.4	Tablet	11
4.5	Router TYP	11
4.6	Sensors	12
4.6.1	Sensor keypads	13
4.6.2	Sensor automatic switching off	13
4.6.3	Low battery warning	13
4.7	Clamps	14
4.7.1	STDA33EU clamps	14
4.7.2	STDA35E clamps (Optional)	14
5	APPLICATION SETTING	15
5.1	Program Configuration	15
5.2	Connecting sensors	18
5.2.1	Internet connection	19
5.3	DATABASE configuration	20
5.3.1	Changing Groups	20
5.3.2	Adding new Groups	21
5.3.3	Info and Database Update	21
6	DIAGNOSIS AND ADJUSTMENT OF A VEHICLE	22
6.1	Selecting the brand and model of a vehicle	22
6.2	Displaying technical data of the selected vehicle	24

6.2.1	Displaying ADDITIONAL MEASUREMENTS on CHASSIS HEIGHTS	25
6.2.2	Displaying CHECK MEASUREMENTS on CHASSIS HEIGHTS	26
6.2.3	Displaying ADJUSTMENT HELP images	27
6.3	Preliminary operations	28
6.3.1	Preliminary vehicle inspection operations	28
6.3.2	Run-Out preparation	28
6.4	Run-Out	28
6.4.1	Push Run-Out procedure with automatic acquisition	28
6.5	Measurement preliminary operations	30
6.6	Aligning and levelling sensors	30
6.7	Steering procedure	31
6.8	Vehicle Diagnosis	32
6.9	Adjustment preliminary operations	32
6.10	Adjusting the rear axle	33
6.11	Adjusting the front axle	34
6.11.1	“Jack-Hold” procedure	35
6.12	Summary of DIAGNOSIS and ADJUSTMENT data	36
6.12.1	Chassis diagnosis	36
6.13	Printing the measurements made	37
6.13.1	Example of table printing	38
6.13.2	Example of graphic printing	39
6.14	Sharing the test carried out	40
6.15	Saving the tests performed with TEq-Link	41
6.15.1	Configuring the TEq-Link function	41
7	FRONT AXLE SPOILER PROCEDURE	42
8	ERROR SIGNALLING	44
8.1	Data transmission error between sensors	44
8.2	Angle measurement error in the horizontal plane	45
9	PROBLEMS	45
10	MAINTENANCE	46
11	DECOMMISSIONING AND SCRAPPING	46
12	MACHINE IDENTIFICATION DATA	47

1 WARNINGS

Any damage resulting from the failure to observe the instructions in this manual and improper use of the machine releases the manufacturer from any liability.

1.1 Preliminary safety information



Before turning on the equipment:

- Read the instructions and the entire manual before using or working on the wheel aligner. This manual is an integral part of the product and is intended to provide the user with instructions on the use of wheel aligner RWA1065. Keep it for the entire operating life of the machine, in a known and easily accessible place and consult it whenever doubts arise. All operators working on the product must be able to read the manual.
- Check that the power supply complies with the specifications on the data plate. The voltage and frequency data plate is located at the back of the equipment. Please note the information on the data plate. NEVER connect the equipment to a voltage or frequency other than those indicated.
- Properly fix the wheel aligner power cord. This product is equipped with a 3-wire plug with built-in grounding. It can be plugged only into a socket that is also grounded. If it is not possible to insert the plug into a socket of this type, please consult an electrician. Do not modify or misuse the plug.

In emergency conditions and before any maintenance work:

- Insulate the machine from energy sources, using the machine's main switch and remove the plug from the power socket.
- Do not attempt to service this unit arbitrarily; maintenance should only be performed by authorized service personnel.

Working environment and equipment cleanliness:

- The working environment must be kept clean, dry, not exposed to the weather and sufficiently illuminated.
- Avoid cleaning the equipment with jets of water and compressed air.
 1. When cleaning plastic panels or shelves use a damp cloth (avoid liquids containing solvents in any case).

The manufacturer may make changes to the models described in this manual at any time for technical or commercial reasons.



TEq-Link brands are owned by manufacturer.

All the other mentioned trademarks, displayed logos and images belong to their rightful owners, which hold all the relevant rights.

2 INTENDED USE

RWA1065 systems are equipment for full detection of characteristic angles of motor vehicles. The angle detection is carried out by four sensors with microprocessor technology and infrared measuring and data transmission system (without using cable connections between the sensors).

The data transmission from the front cab sensors is performed VIA RADIO by means of modules



The maximum permissible length of the vehicle wheelbase, to allow data transmission and angle measurement, is 6000mm/236".

Temperature range for the use of the equipment between 0 and 40°C.

3 TRAINING OF THE PERSONNEL

Only specially trained and authorized personnel are allowed to use the equipment. In order for the machine to be operated optimally and for measurements to be carried out efficiently, it is necessary for the personnel in charge to be properly trained to learn the necessary information in order to achieve an operating mode in line with the manufacturer's instructions. For any doubt regarding the use and maintenance of the machine, consult the instruction manual; in case of doubts do not interpret it, but consult the authorized service center or directly the technical assistance.

3.1 General preventive measures



- When operating and maintaining this machine, it is imperative to comply with all applicable safety and accident prevention regulations.



- The equipment must only be used by authorized and properly trained personnel.



- This equipment should be used only for its intended use. The supplier declines all liability for damage to people, animals and things caused by improper use of the machine.



- The installation of accessories and spare parts must be carried out by personnel authorized by the manufacturer using only original accessories and spare parts



- The machine must operate only in places where there is no risk of explosion or fire.



- Removal or modification of safety devices or warning signs on the machine may cause serious danger and constitutes a violation of the OSHA safety standards.

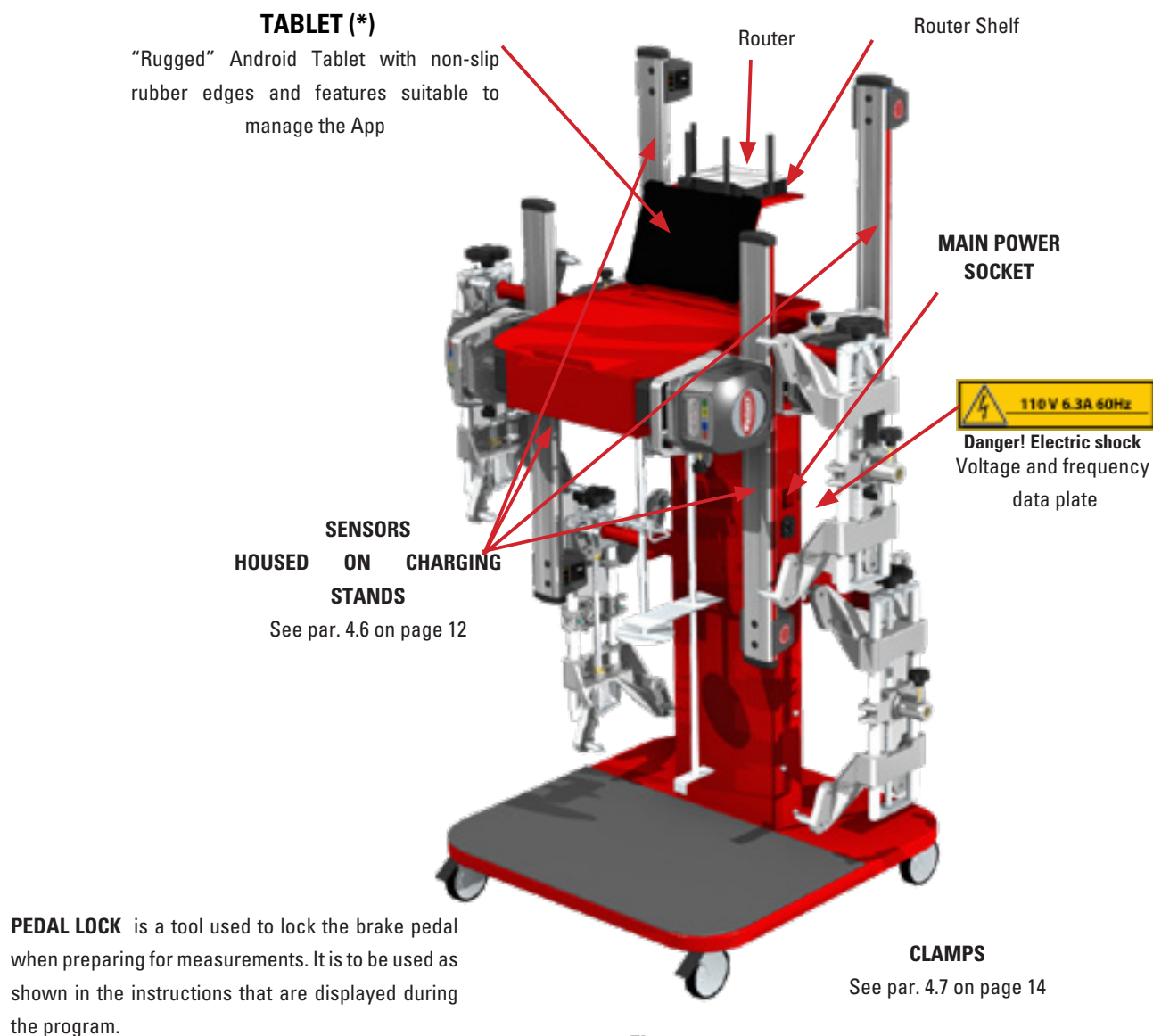


- Before performing any maintenance work on the system, the power supply must be switched off. In case of doubt do not interpret, please contact the technical assistance in advance in order to receive instructions on how to carry out operations in conditions of maximum safety.



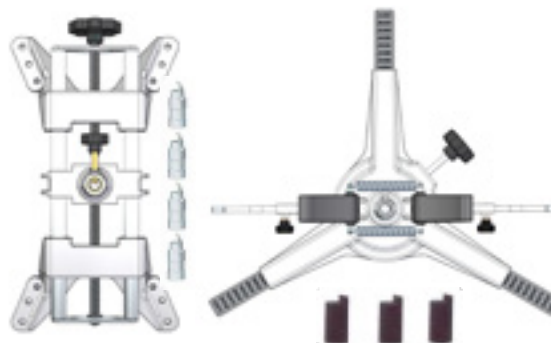
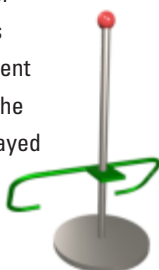
- Do not allow unauthorized personnel to approach the wheel aligner during use.

4 COMPOSITION OF THE EQUIPMENT



- Figure 1 -

STEERING LOCK is a tool used to lock the steering wheel in a fixed position. It is used prior to the adjustment procedure as shown in the instructions that are displayed during the program.



4.1 Clamp compartment (optional)

4.1.1 STDA156 (wall-mounted panels)

2 embossed thermoformed wall-mounted panels are available as an option in a size similar to that of sensor panels. For the fixing with the supplied dowels, refer to the installation instructions supplied separately.



- Figure 2 -

4.1.2 STDA155 (clamp trolley)

A trolley for clamps, pedal lock and steering lock is available as an option.



- Figure 3 -

4.1.3 STDA157 (wall hooks)

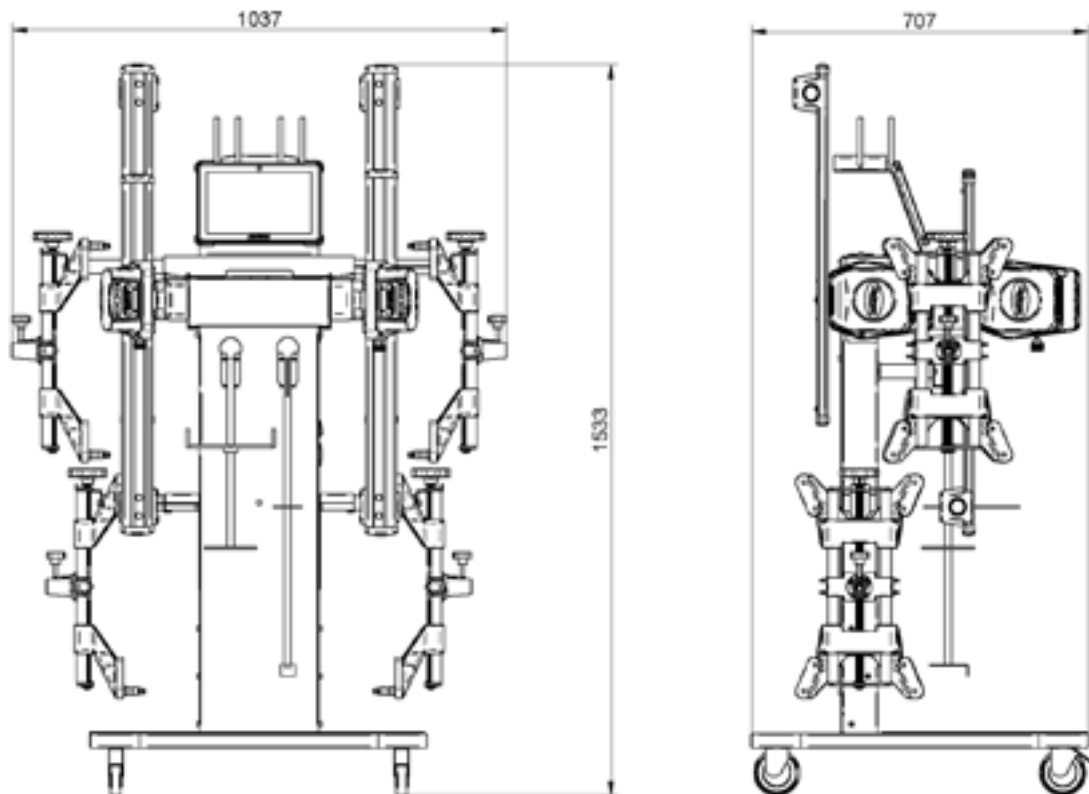
No.4 hooks are available as an option to fix clamps to the wall with dowels.



4.2 Measuring ranges and accuracy

Axle	Measurement	Accuracy	Measuring range	Total measuring range
Front	Total toe	$\pm 2'$	$\pm 2^\circ$	$\pm 20^\circ \times 2$
	Partial toe	$\pm 1'$	$\pm 1^\circ$	$\pm 20^\circ$
	Set-back	$\pm 2'$	$\pm 2^\circ$	$\pm 5^\circ$
	Camber	$\pm 2'$	$\pm 3^\circ$	$\pm 10^\circ$
	Caster	$\pm 5'$	$\pm 10^\circ$	$\pm 18^\circ$
	King-pin	$\pm 5'$	$\pm 10^\circ$	$\pm 18^\circ$
Rear	Total toe	$\pm 2'$	$\pm 2^\circ$	$\pm 20^\circ \times 2$
	Partial toe	$\pm 1'$	$\pm 1^\circ$	$\pm 20^\circ$
	Set-back	$\pm 2'$	$\pm 2^\circ$	$\pm 5^\circ$
	Camber	$\pm 2'$	$\pm 3^\circ$	$\pm 10^\circ$
	Thrust angle	$\pm 2'$	$\pm 2^\circ$	$\pm 5^\circ$

4.3 Overall dimensions



- Figure 4 -

4.4 Tablet

Depending on the equipment purchased, a “Rugged” Android tablet with non-slip rubber edges may be included. The Device is supplied with features (see minimum characteristics below) suitable to manage the Aligner APP CCD2.0WiFi.

The table shows the minimum requirements for the operation of the APP:

Operating system	Android ver. 6
Video Resolution	1280 x 800
Processor	1 GHz dual core
Internal storage / RAM	12GB/ 2GB

If you are using a IOS device it is necessary to use tablets with operating system starting from ver. 12. A magnet KIT is included in the equipment supply, which can be glued at the back of the tablet, so that it can be attached directly to the lift. You can also hang it on the vehicle, using the hook provided, highlighted below in blue, which is used to hook it onto the panel (See - Figure 1).



- Figure 5 -

4.5 Router TYP

The composition of the equipment includes an Access Point that generates a WiFi network called “connect”, to which the front sensors and the Tablet are connected, thus allowing the transmission of data between Tablet and sensors.



(*) Note: by connecting the WAN port to a data structure access socket with Internet access, you can use the functions needed, see also references on the quick guide code M0335.

You can also temporarily (at the appropriate stages) select a WiFi network with Internet access. The switching between “Internet” and sensor “connect” networks can also take place automatically (See 5.2.1 on page 19).



To set configurations different from the one set at the factory, for example to use a pre-existent Wi-Fi network also for sensors, contact the support service authorised by the manufacturer.

4.6 Sensors

The sensors do not need the connection of any cable or lanyard for angle measurement.

The sensors units consist of infrared data transmitters/receivers and CCD-type transducers with infrared emitter focal point.

All the characteristic angles of both vehicle axles are controlled by 8 CCD sensors with infrared measurement. Measurement with the infrared system is always effective even in critical lighting conditions.

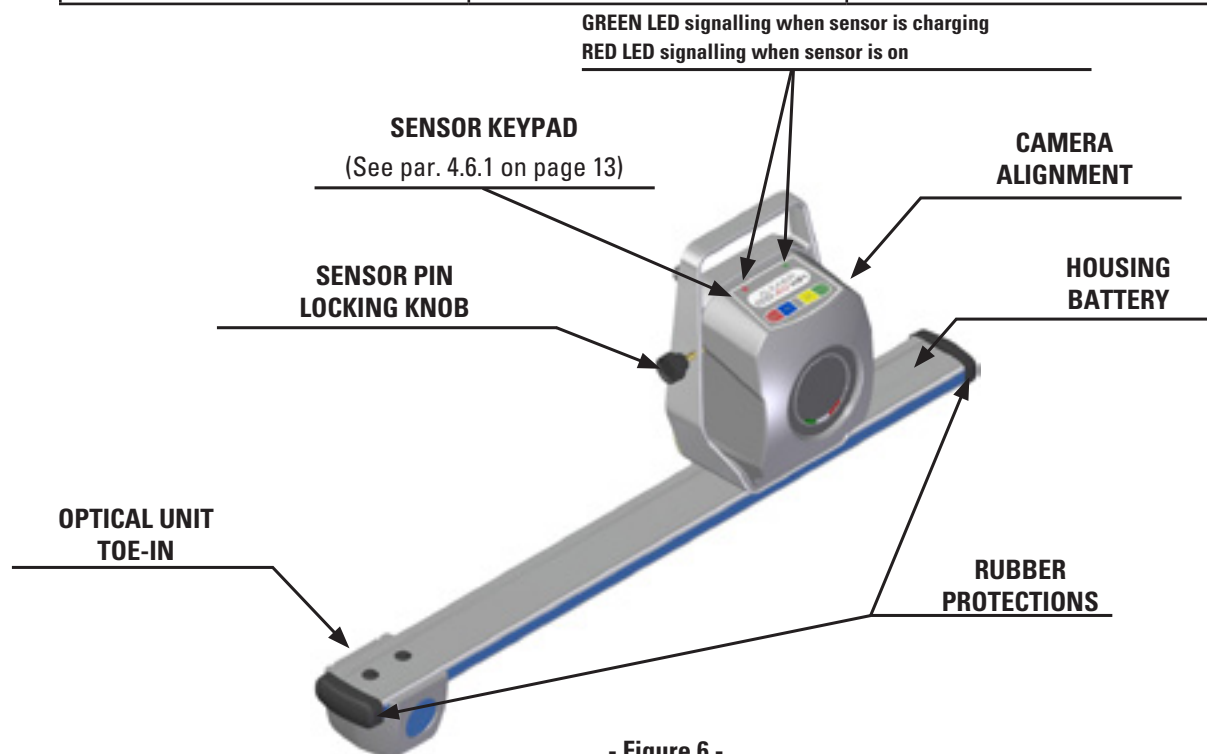
The front sensors communicate via  modules with the control device (Tablet), connecting to the WiFi network generated by the Router (See Chap. 4.5 on page 11)

The data from the rear sensors are transmitted/received by passing through the front sensors, using the infrared transmission.

The power supply is provided by 6V long-life rechargeable batteries. The batteries of the front and rear sensors are recharged by means of the special charging stands (See - Chap. 4 , - Figure 1).

Rechargeable battery power data and consumption are as follows:

	REAR SENSORS	FRONT SENSORS
Power supply	NiMH battery 6V - 2000mAh	NiMH battery 6V - 2000mAh
Average operation with fully charged battery in full efficiency	About 12 hours	About 10 hours
Average recharge time	About 10 hours	About 10 hours



- Figure 6 -

4.6.1 Sensor keypads



- Figure 7 -

KEYS		DESCRIPTION
		Sensor power key.
		Pressed at the same time, they manually switch off the sensor.

Key of the - Figure 7:

A-	• Green LED on:	the sensor battery is charging
B-	• Red LED steady on:	the sensor is on
	• Red LED flashing:	the sensor battery is low (when the remaining battery charge is less than or equal to 30%); it will switch off after a few minutes.

4.6.2 Sensor automatic switching off

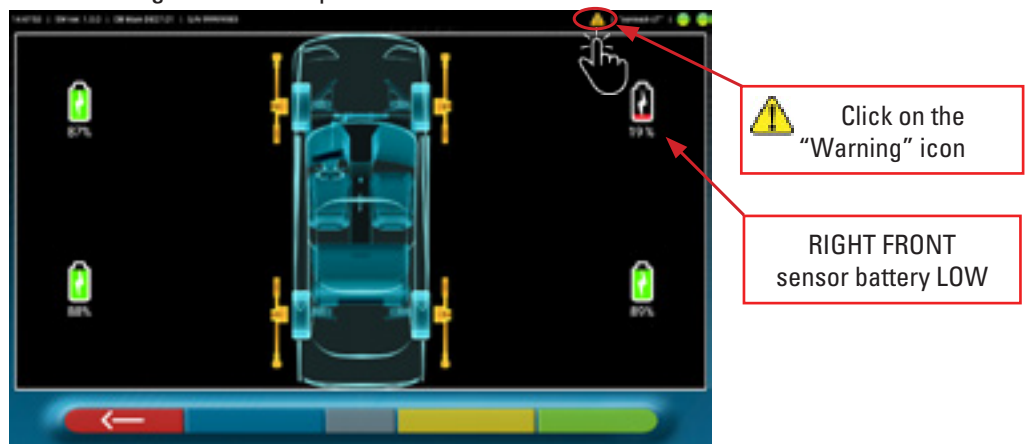
The sensors turn off automatically after approx. 5 min. if they are not receiving data, i.e. when the program is in a phase where no data is transmitted/received for the measurement (e.g. on the home page) or if the tablet is switched off. It is always possible to turn off the sensors manually (See tableau au par. 4.6.1) when they are not being used.

4.6.3 Low battery warning

When the residual charge of one or more sensors is LESS than or EQUAL to 30%, the program displays a “Warning” ⚠️ symbol to indicate an error condition (See chap. 8 on page 44).

Click on the “Warning” symbol to display the “low battery” error page showing the charge percentage (- Figure 8). This warning appears also the sensor through the flashing of the red power-on LED (See par. 4.6.1 on page 13).

You must put the sensor back in charge as soon as possible.



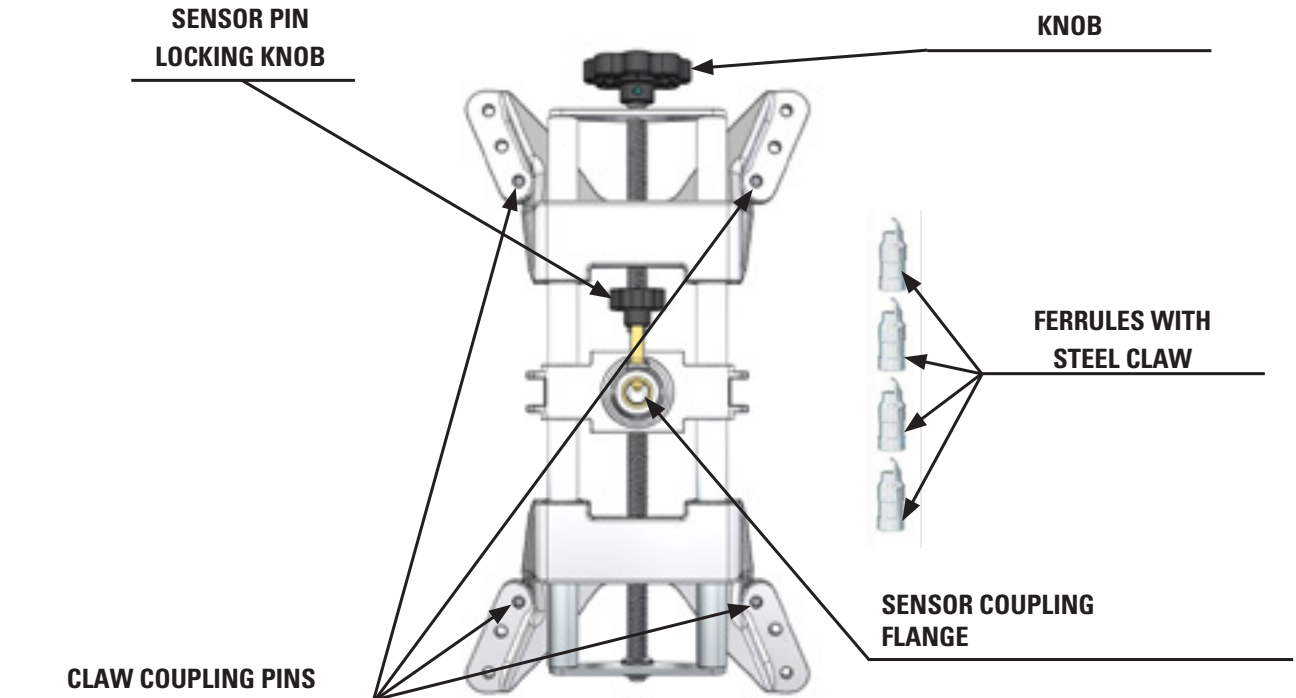
- Figure 8 -

To quit the warning page press key. 

4.7 Clamps

4.7.1 STDA33EU clamps

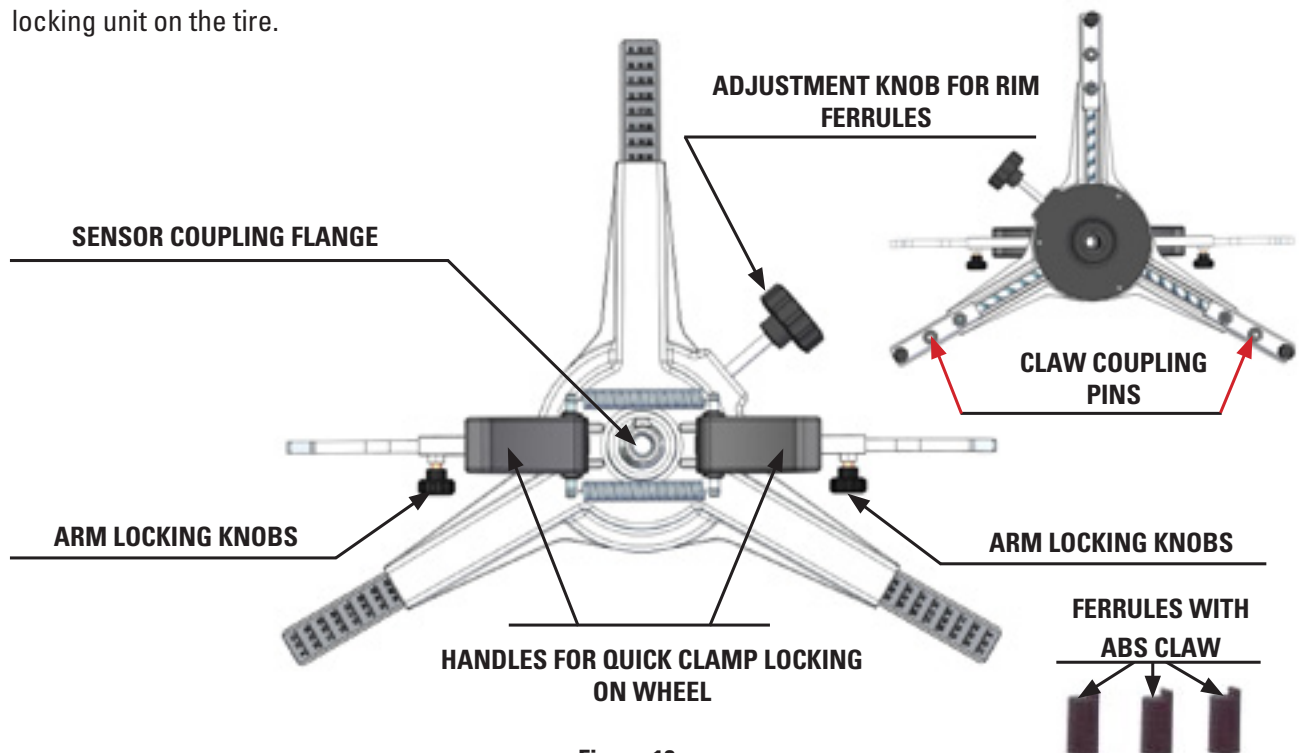
STDA33EU clamps are self-centering screw type for alloy wheels from 10 to 24 ", with removable fingers.



- Figure 9 -

4.7.2 STDA35E clamps (Optional)

STDA35 clamps are of the 3-point self-centring type for alloy wheels from 10" to 24" with manual approach and locking unit on the tire.



- Figure 10 -

5 APPLICATION SETTING

5.1 Program Configuration

To start the CCD2.0WiFi program click on the icon  ; the program starts and the overview page is displayed on the Tablet, from which you can access all the main functions of the equipment. .

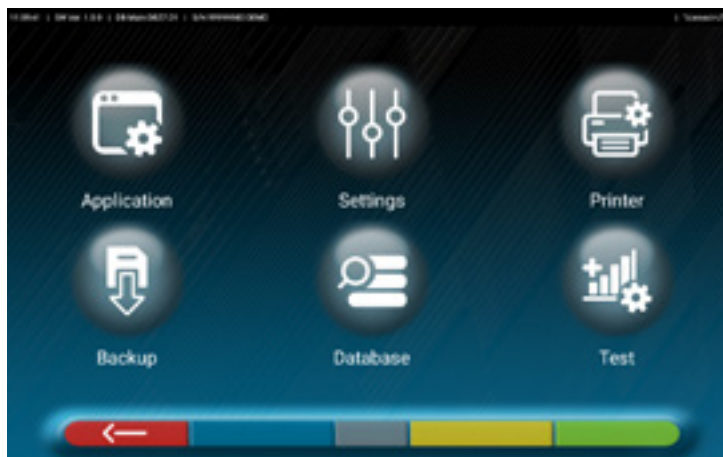
Important !: the functions actually available may depend on the type of device and the version of the operating system you are using.



- Figure 11 -

Select key  to continue and start vehicle diagnosis and adjustment procedure (See par. 6 on page 22).

Select key  to execute the program configuration, you will access a configuration menu that allows you to vary the characteristics of the application according to your needs See - Figure 12.



- Figure 12 -

Below are the different possible options related to each of the menus indicated in: - Figure 12



Application: - Figure 13 You can activate and set up features that may be available in your configuration as TEq-Link (par. 6.15 on page 41). It is possible to perform WiFi search for the connection of front sensors to the network shared with the Tablet (par. 5.2 on page 18). Set the automatic switchover between "Internet" and "connect" networks (See 5.2.1 on page 19). You can configure the sounds associated with events during adjustment or run-out.

You can also set the "Demo" mode and access the license activation (see info on quick guide code M0335) and the info on the CCD2.0WiFi App.



- Figure 13 -



Settings: - Figure 14 - The parameters regarding units of measurement and angle resolution can be edited: set the "STANDARD" or "USA" toe-in calculation method or display separate tolerances between left and right side.

You can also customise particular wheel alignment procedures such as displaying right- or left-hand drive graphics, and insert search filters on vehicle displaying from log sources.



- Figure 14 -



Printer: - Figure 15 - In the "Printer" menu you can customise the print report by entering the data at the workshop; you can select the desired type of print (in graphic or table format) and choose the fields you want to enter that will then be displayed in the report (operator, km travelled, chassis number, etc. ...).



- Figure 15 -



Data base: - Figure 16- In the “Database” menu you can configure groups with different brands at will, update the database and read the disclaimers of the data suppliers. See par. 4.3



- Figure 16 -



Test: - Figure 17 - In the “Test” menu various options are available for the analysis of the functionality of the different sensor measuring devices. Instructions for these operations are provided separately and reserved to skilled personnel authorised by the manufacturer.



- Figure 17 -



Backup: - Figure 18 - In the “Test” menu there are options to save and restore the set configurations, or restore the factory default App settings.



- Figure 18 -

To go back to the configuration menu (- Figure 12-), press key



5.2 Connecting sensors

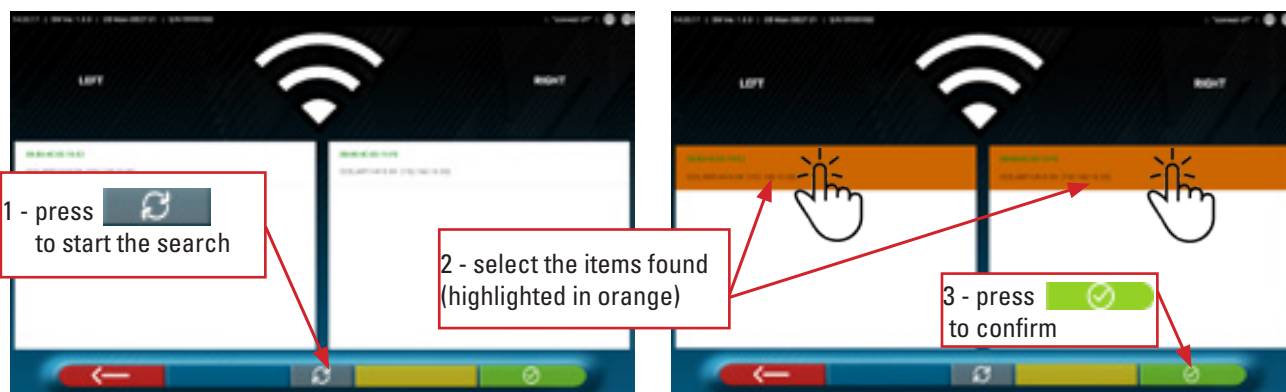
Before starting to use the wheel aligner SW, if you have not done it before, you must connect the front sensors with the Tablet, through the “WiFi Search” procedure of the configuration menu (See - Figure 12-) Application > Wifi Search > Wifi Scan.



 you must first connect the Tablet to the WiFi network “connect” - See par. 4.5

- Figure 19 -

The page (- Figure 20-) is displayed, where you need to press key  to start sensor search. When the sensors are found, select the two items (they will be highlighted in orange) and press key  to confirm.



- Figure 20 -

The connection status of the 2 front sensors is shown on the top right side:

Front left and right sensors are connected to the Wi-Fi and ready to communicate with the tablet >  

Front left and right sensors are not connected to the Wi-Fi (e.g.: they are off) >  



Sensors connected

- Figure 21 -

5.2.1 Internet connection

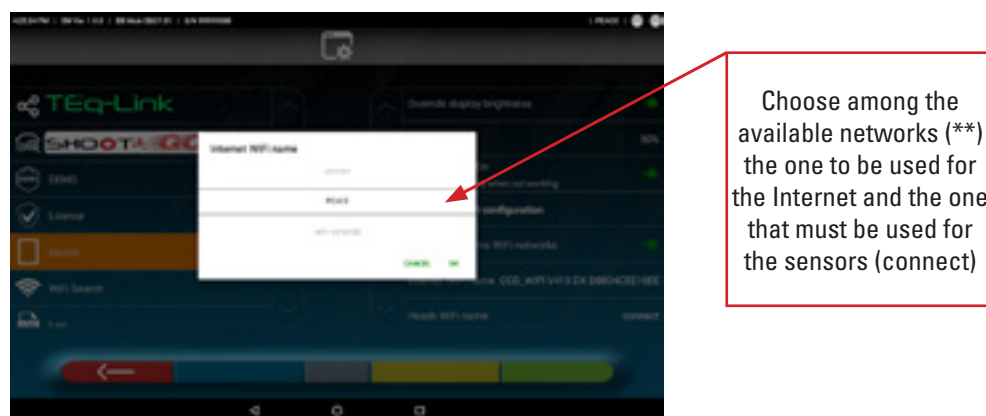
In order to be able to use the features that require an Internet connection (TEq-Link, print report sharing) the WAN port of the Router must be connected to a data structure access socket with Internet access (See par. 4.5 on page 11).

However, it is also possible to obtain an Internet connection by temporarily using an alternative WiFi network (*). The switching between Internet and “connect” sensor networks can be set automatically:

From the configuration menu (See - Figure 12 on page 15) access Application > Device > and enable the alternative WIFI network with the  Onselector switch



- Figure 22 -



- Figure 23 -

The CCD2.0WiFi application properly manages the switching from the “Internet” network to the “Sensors” network:

- Upon start-up it always connects to the “Internet” network.
- During the Run-Out preparation stage, where you need to connect to the sensors (See - Figure 43 on page 28), it connects to the “Sensors” network (connect).
- At the end, when entering vehicle and customer data (See - Figure 61 on page 37), it connects again to the “Internet” network.

Note () The Internet connection via the WAN port of the Router guarantees maximum performance. For this reason, it is not recommended to use an alternative WiFi network where the positioning of the antennas and network traffic (overcrowding due to other connected devices) cannot be easily controlled.*

*Note (**): For Android devices it is sufficient that the networks in question are stored in the device.*

For IOS devices it is necessary to set, in addition to the “Internet” and “Sensors” networks, the relevant passkeys (they must be WPA2-PSK).

5.3 DATABASE configuration

You can customise the vehicle database, choosing which “groups” to show, or you can create new groups or modify the existing ones by adding or removing brands.

You can view information about the existing databases or check for new updates

Select the “DATABASE” option  in the program configuration page - See par. 5.1, - Figure 12 - then select Brand Groups > Configure



- Figure 24 -

5.3.1 Changing Groups

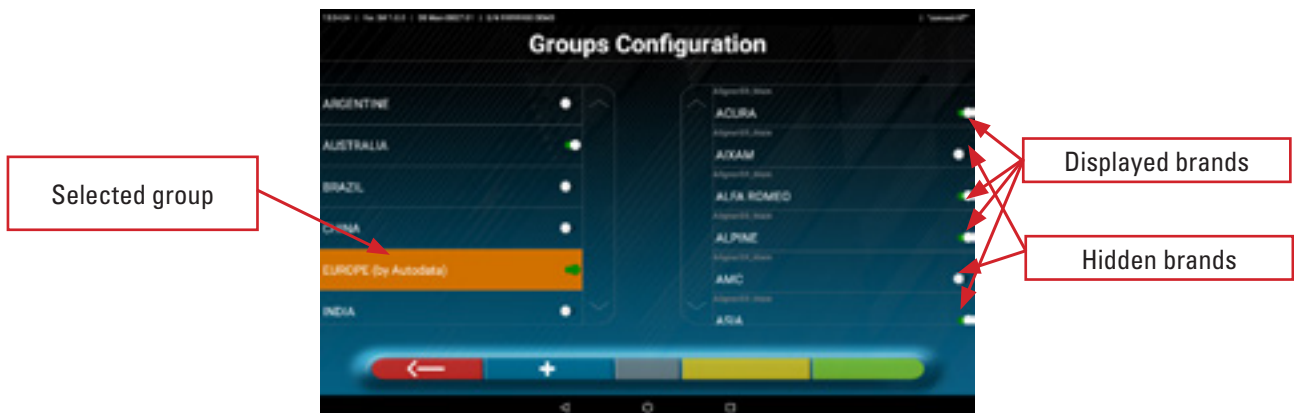
The page of - Figure 25 displays a list, with the different “profiles” (groups) of the DATABASE, containing the BRANDS of vehicles in circulation in different countries or regions of the world.

Through the  On/  Off switch selectors , you can hide and/or display any group in order to manage the Database according to your needs.



- Figure 25 -

Selecting a group you can also customise it by hiding and/or displaying the brands present, always through the  On/  Off switch selectors .



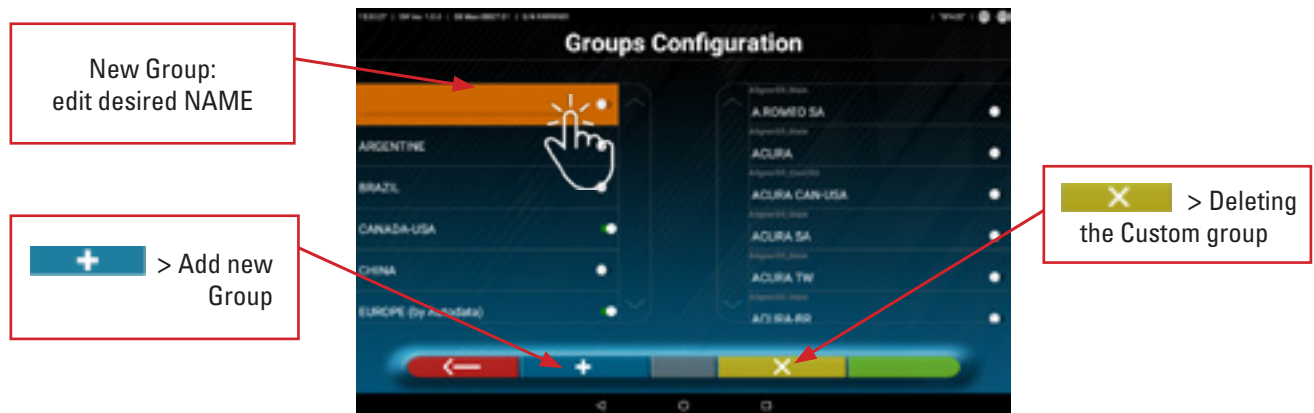
- Figure 26 -

5.3.2 Adding new Groups

You can also create a new custom group and enter the required brands in it.
Click on key ,  a new entry is generated at the top of the group list.
Edit the field highlighted in orange with the name of the desired group.

Then use the  On/  Off switch selectors to set the brands to be displayed within the new Group.

Note: to remove a custom group click on key 



- Figure 27 -

5.3.3 Info and Database Update

By clicking on the “updates” icon you can view information on the configuration and version of the databases present, you can also check the availability of new updates and, if necessary, download them (you must have an Internet connection for this - see quick guide code M0335).



- Figure 28 -

6 DIAGNOSIS AND ADJUSTMENT OF A VEHICLE

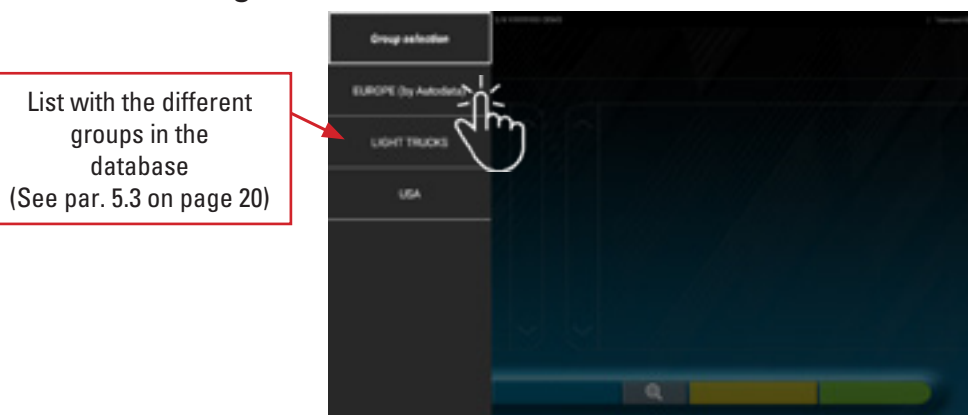
To start the CCD2.0WiFi program click on the icon ; the program starts and the home page (- Figure 29) from which you can access the main functions of the equipment, will be displayed.



- Figure 29 -

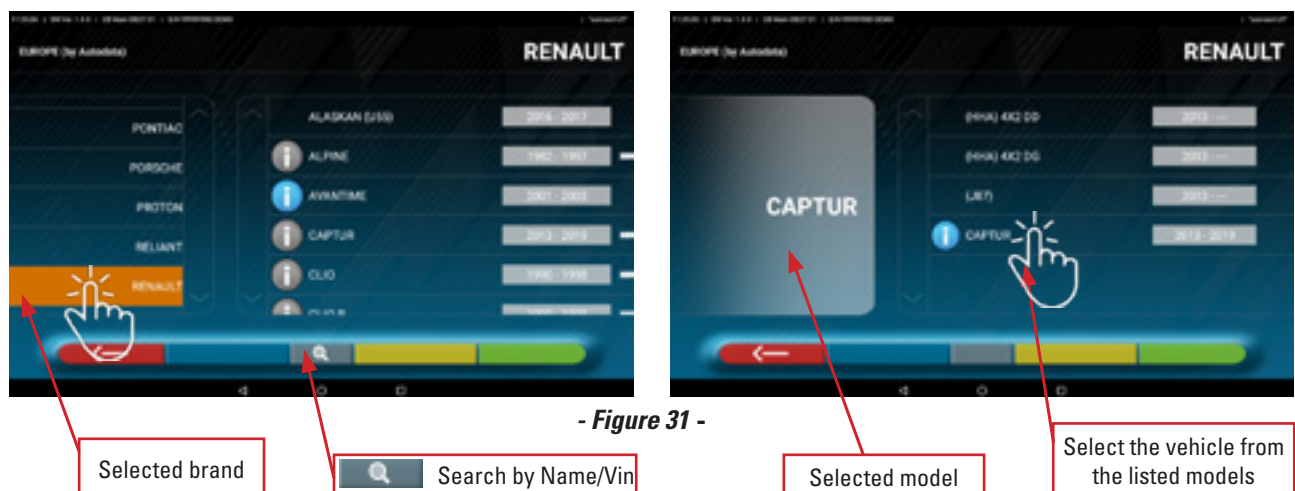
Use key  to continue with the selection of the vehicle in the database (See par. 5.1)

6.1 Selecting the brand and model of a vehicle



- Figure 30 -

Select the group from those available, the program shows the list of brands of the selected group (See - Figure 31). Scrolling up and down the lists, select the brand of the vehicle and then the model.



- Figure 31 -

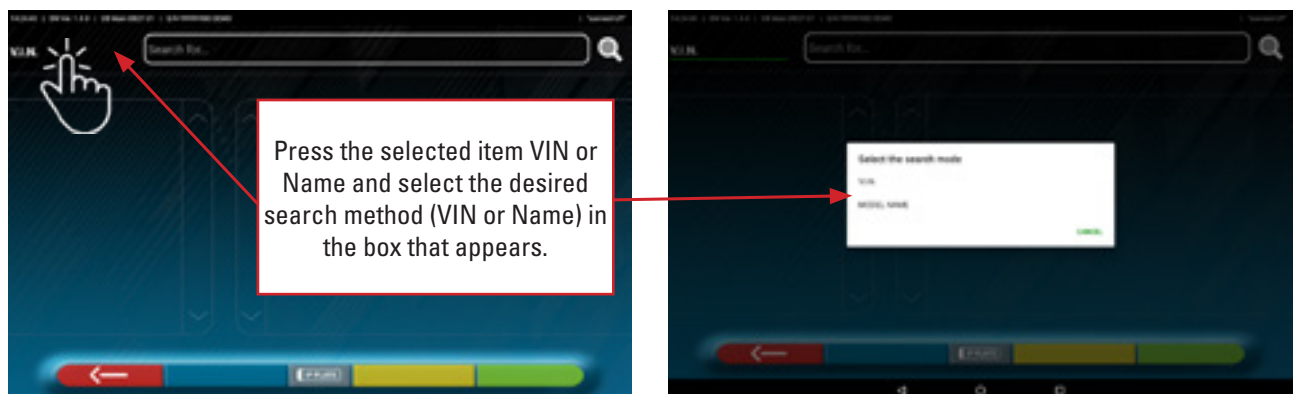
Pressing key from  - Figure 31-, you can select the search method by name.

Type the model name in the box and press the icon , the vehicle or group of vehicles found in the database will be displayed.



- Figure 32 -

Note: if the USA-MOTOR database is present in the device, the search method can be set by "Name" or V.I.N (*) , See - Figure 33.



- Figure 33 -

(*) The V.I.N. (Vehicle Identification Number) is a unique serial number used in the automotive industry to identify motor vehicles. It consists of a plate with 17 alphanumeric characters usually located inside the engine compartment.

To set the vehicle selection method "group/brand/model" (- Figure 31-), again, press the central key  in the screen of - Figure 32 -.

NOTE: It is possible to enter the VIN CODE manually using the virtual keyboard on the tablet or through a BARCODE SCANNER device connected via BTH (Please, ask the manufacturer for compatible models).

6.2 Displaying technical data of the selected vehicle

After having selected the vehicle (See par. -6.1 e -5.2), a screen with the measurements and angle tolerances (minimum, middle and maximum value) and other additional data, such as rim diameter, wheelbase, track width and any loading and tank conditions (*) (- Figure 34 -) will appear.



- Figure 34 -

The screen with measurements and tolerances can be represented as in - Figure 34 -: with a single column of homogeneous values for the left and right sides.

In the "Settings" menu (See - Figure 14 on page 16) it is also possible to set the displaying of data separated between left and right sides (some vehicles may have slightly different tolerance values for left and right sides).

By pressing key  it is also possible to display the measurements with the middle value and the total tolerance "±" (See - Figure 35).



- Figure 35 -

Press key  to continue with the preliminary operations on the vehicle (See -par. 6.3 on page 28)



(*) The device with the CCD2.0WiFi APP contains vehicle technical information provided through official databases. Access to the system and information is subject to reading and accepting a Disclaimer, which is shown on the device after the first start of the APP.

6.2.1 Displaying ADDITIONAL MEASUREMENTS on CHASSIS HEIGHTS

Some manufacturers (e.g. Mercedes, Renault) provide the angle tolerance values according to particular measurements on the vehicle chassis.

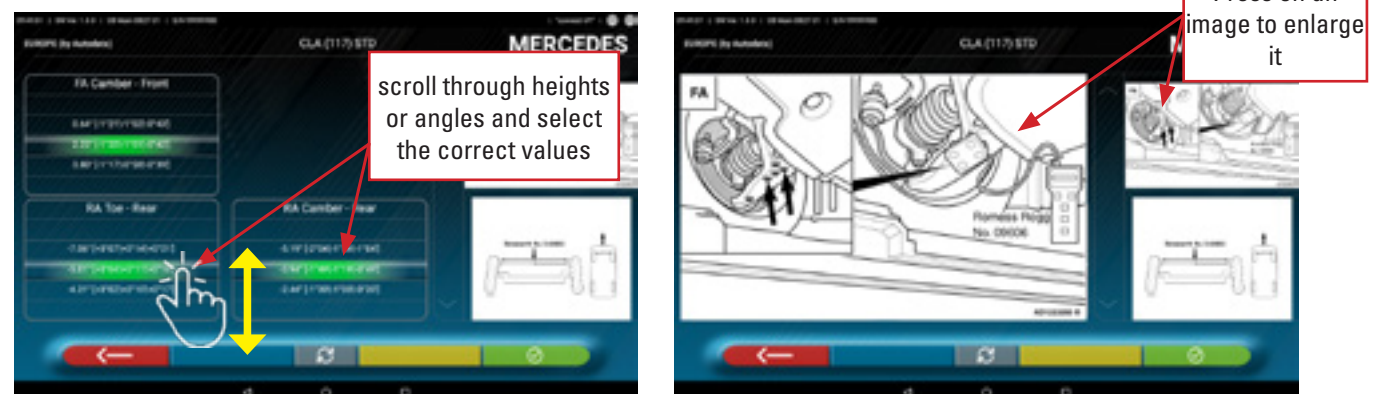
When the selected vehicle has angle tolerance values linked to additional measurements on the chassis, key  is present on the technical data page (- Figure 36-). Press the key to display the page with details on chassis measurements.



- Figure 36 -

The program displays a page as in the example of - Figure 37- , use the scroll bar to view the different images, press on an image to enlarge it.

Scroll through the different heights/angles in the tables and select the correct values.



- Figure 37 -

The measurements can be entered by selecting them from the tables, as in the example above - Figure 37- , or by pressing key  a page is displayed, as in the example above - Figure 38-, where you can directly enter the values.



- Figure 38 -

Press key  to confirm the entered values

6.2.2 Displaying CHECK MEASUREMENTS on CHASSIS HEIGHTS

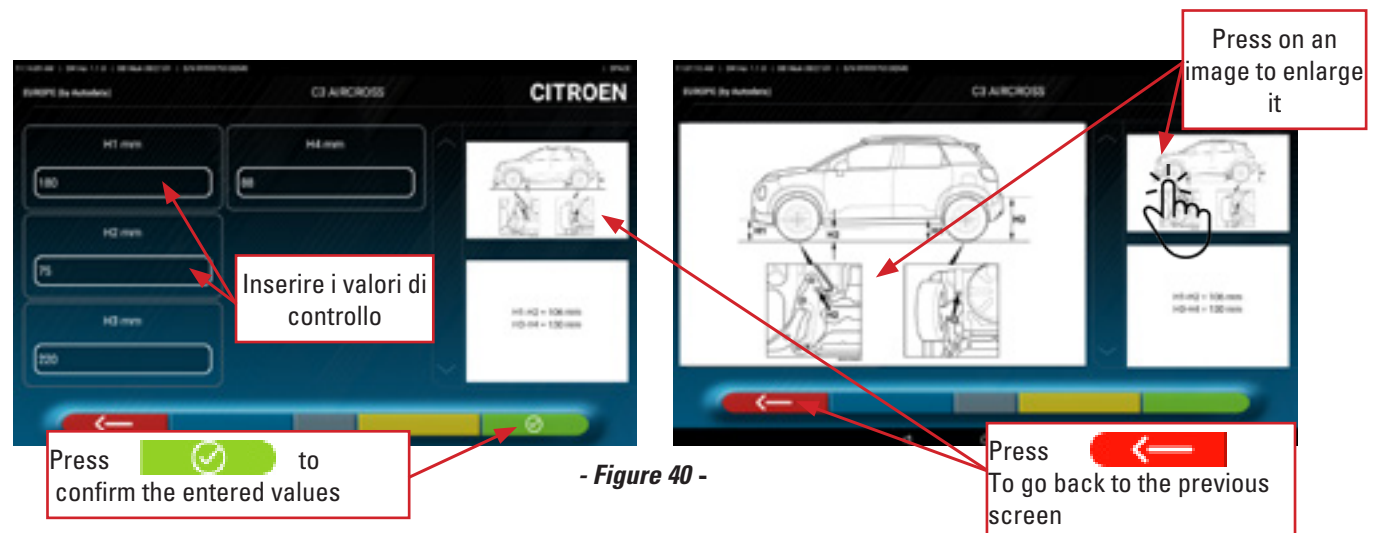
Some manufacturers (e.g. Citroen, Peugeot) provide tolerance values for particular measurements on the vehicle chassis (check values).

When the selected vehicle has tolerance values with check values, key  is present on the technical data page (- Figure 39 -) Press the key to display the page with the details of the check values.



- Figure 39 -

The program displays a page as in the example of - Figure 40, use the scroll bar to view the different images, press on an image to enlarge it.



- Figure 40 -

Enter the check values directly, and press key  to confirm the entered values.

6.2.3 Displaying ADJUSTMENT HELP images

For several vehicles of some manufacturers, adjustment help images are available, which indicate how to adjust the different angles of the vehicle, such as front axle camber and caster angles or rear axle camber and total toe.

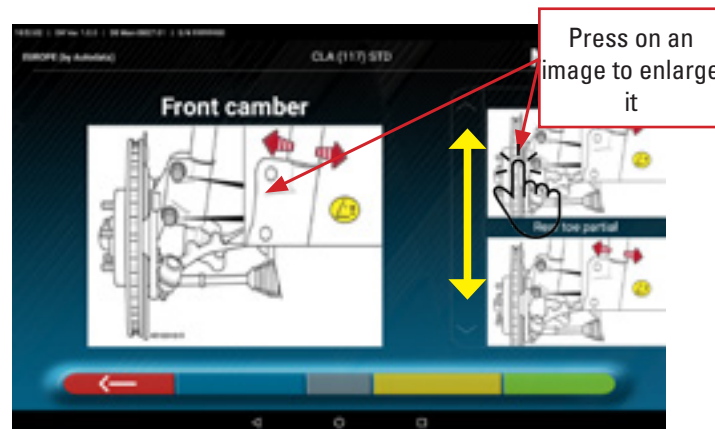
When the selected vehicle has adjustment help images, the technical data page (- Figure 41-).includes key .

 Press the key to display the adjustment help images.



- Figure 41 -

The program displays a page as in the example of - Figure 42-, use the scroll bar to view the different images, press on an image to enlarge it.



- Figure 42 -

Press key  to go back to vehicle's technical data page.

Note: also during the rear or front adjustment (par. 6.9 on page 32 and par. 6.11 on page 34), if there are adjustment help images, key  is available to view them if necessary.

6.3 Preliminary operations

6.3.1 Preliminary vehicle inspection operations

Before checking vehicle wheel alignment, a few preliminary checks must be performed:

- Check and, if necessary, eliminate any play on the suspensions and steering linkage.
- Check and, if necessary, eliminate any hardening or yielding of the suspension flexible components.
- Adjust the tyre pressure to the values prescribed by the manufacturer.
- Position and distribute any loads foreseen by the manufacturer

6.3.2 Run-Out preparation

After displaying the vehicle technical data (See par. 6.2 on page 24) press on key  to continue, the page showing the preparation of - Figure 43 - Figure 48 the vehicle for the Run-Out procedure will be displayed:

- Lock the turntables
- Position the vehicle with the front wheels on the turntables
- Fit clamps and sensors on the wheels



- Figure 43 -

Note: in this step, images representing the 4 sensor batteries with relevant remaining charge % are displayed.

6.4 Run-Out

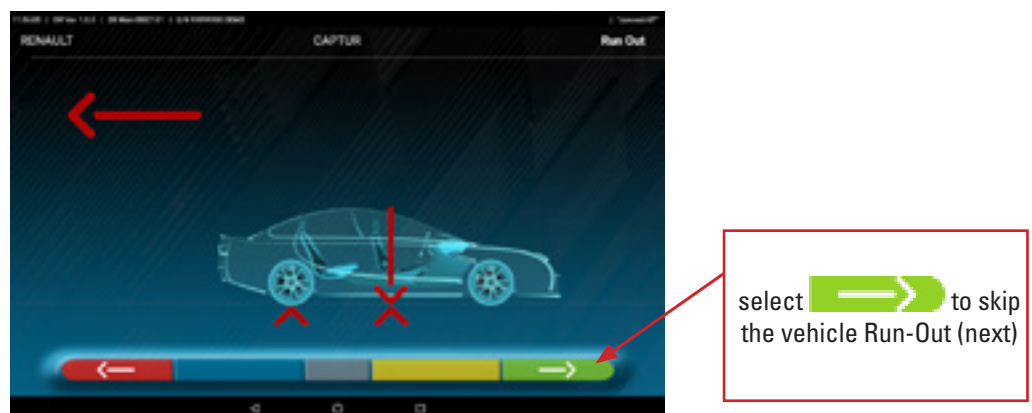
The Run-Out procedure is carried out to compensate for any deviation between the plane passing through the wheel and the one actually measured.

This procedure can however be skipped, when required, with key  (See - Figure 44-).

6.4.1 Push Run-Out procedure with automatic acquisition

In the Run-Out preparation phase (See par. 6.3.1 on page 28) select key  . The following screen appears.

To perform the Run-Out operation, always follow the visual instructions on the screen.



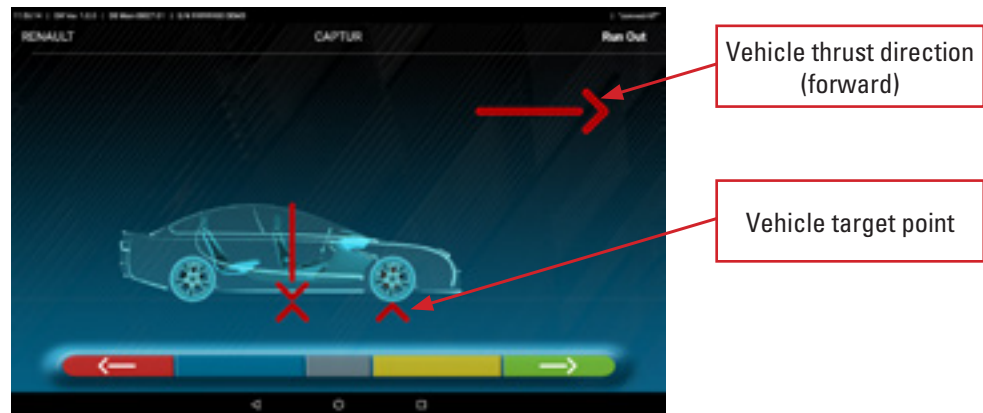
- Figure 44 -

UNLOCK the sensors using the appropriate knob (See - Figure 6) so that they are free to rotate and allow for vehicle movement. Move the vehicle backwards, very slowly, until the arrow on the vehicle reaches the target point.



- Figure 45 -

As soon as the vehicle is aligned with the target point, wait for the sensors to stop swinging, "STOP" is displayed for about three seconds, which is the time it takes the program to acquire the measurements. Then the program displays the following screen:



- Figure 46 -

Move the vehicle forward again, until the arrow on the vehicle matches the target point (end point), "STOP" is displayed for about three seconds, measurements are acquired. The Push Run-Out procedure has been performed.

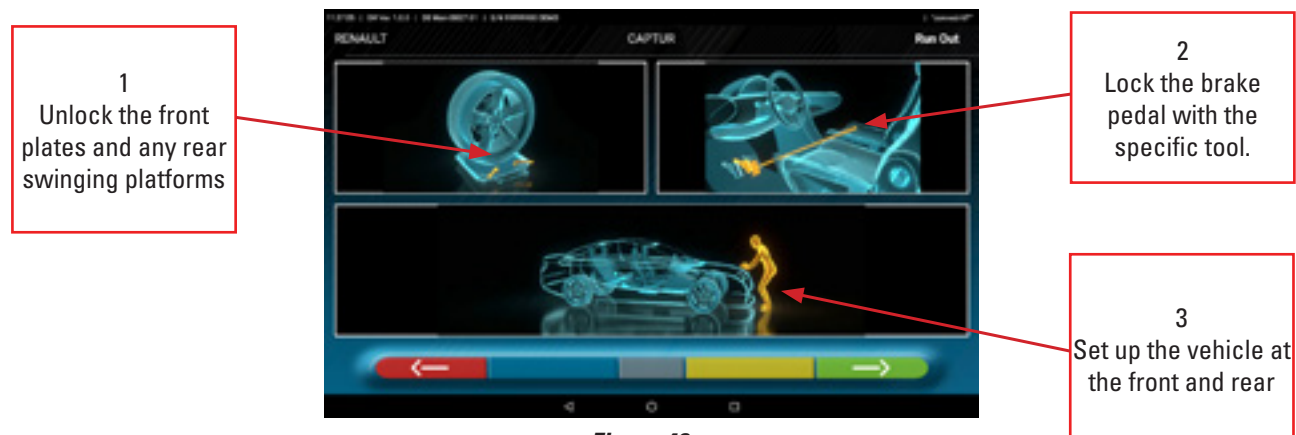


- Figure 47 -

When the Run-Out has been performed, the program automatically continues to the next step: Measurement preliminary operations (par. 6.5 on page 30).

6.5 Measurement preliminary operations

After performing the Run-Out procedure, as explained in par. 6.4 on page 28, it is necessary to prepare the vehicle for measurements. The following screen will appear:



- Figure 48 -

- 1) Unlock the front plates and any rear platform
- 2) Brake the wheels with the handbrake and lock the brake pedal with the specific tool (in case of steering, this is necessary to correctly calculate the steering axis inclination and caster angles).
- 3) Set up the vehicle at the front and rear. This operation is necessary if the vehicle has been previously lifted with the suspension released (e.g. running Run-Out with raised wheels).

Press key  to go back to the Run-Out run-out procedure (par. 6.4 on page 28)

Press key  to continue with the alignment (par. 6.6 on page 30).

6.6 Aligning and levelling sensors

After having carried out the preparation for the measurements as explained in par. 6.5 on page 30, the screen of - Figure 49-; will be displayed; the alignment and levelling procedure of the sensors must be carried out:



- Figure 49 -

Turn the steering wheel from left to right, or vice versa, until the wheels are aligned, i.e. until the display level appears at the centre;

Adjust the sensors until they are levelled and brake them using the suitable knobs. This operation must be performed for all four sensors.

After the sensors have been aligned and levelled, a "STOP" signal image appears, indicating that the program is taking measurements, then the program continues automatically.

WARNING: The vehicle on which operations are being carried out may be equipped with a front Spoiler preventing the sensors from communicating with each other. In this case the special "spoiler" procedure is automatically started.

(See par. 6 on page 22).

6.7 Steering procedure

After performing the alignment and levelling procedure on sensors (See par. 6.6 on page 30), the screen of - Figure 50 ; appears, in which you can carry out the steering procedure, which is used to determine the angle measurements relating to:

- Caster angle - King pin - Included angle

Following the directions on the screen, turn the steering wheel to bring the level of the display to the target point highlighted in green, first to the left, then to the right and finally to the center.

After the wheels have been moved back to the center, the program will continue automatically and will show the diagnosis page. (par. 6.8 on page 32).

Note: The steering procedure can also be skipped by selecting key  The values of the above mentioned measurements will not be displayed and the diagnosis page will be directly displayed (par. 6.8 on page 32).



- Figure 50 -

(*) Steering mode for acquisition of Caster angle/king pin

-  > 10° steering
-  > 20° steering
-  > ACKERMANN steering (20° with steering geometry)

(**) Maximum steering:

Selecting key **MAX**, the page on the side appears (- Figure 51-), where it is possible to manually enter the maximum steering values that are used to evaluate the centring of the steering box. These must be read on the turntable graduated scale.

After entering the values confirm with key .

The maximum steering values will be reported on the final print report.

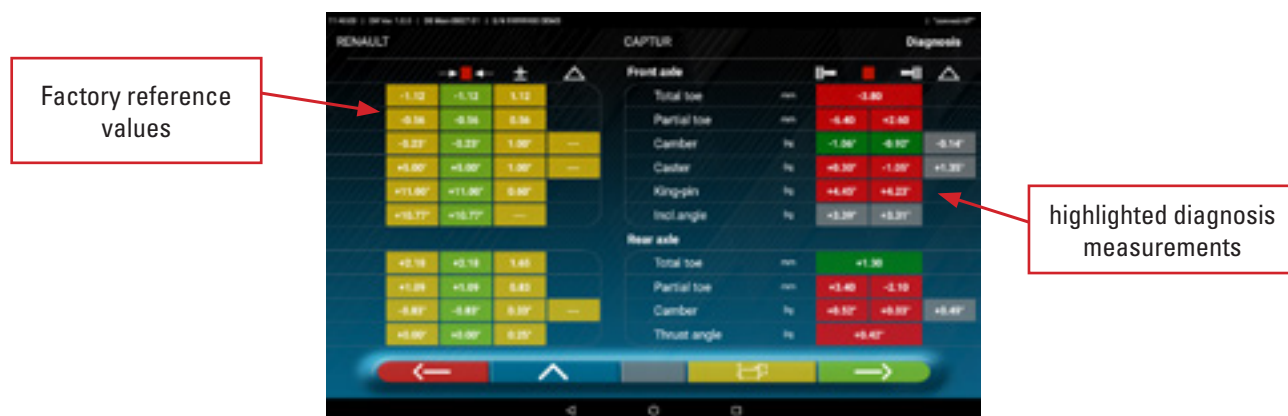


- Figure 51 -

6.8 Vehicle Diagnosis

After having carried out the steering procedure (See par. 6.7 on page 31), a page showing the summary of the measurements made (- Figure 52 on page 32).

The factory reference values are indicated on the left, while the right side shows the diagnosis measurements; the values are highlighted in green if within tolerance, in red if out of tolerance, in grey if the tolerances are not present.



- Figure 52 -

Press key to go back to the procedure steering procedure (par. 6.7 on page 31).

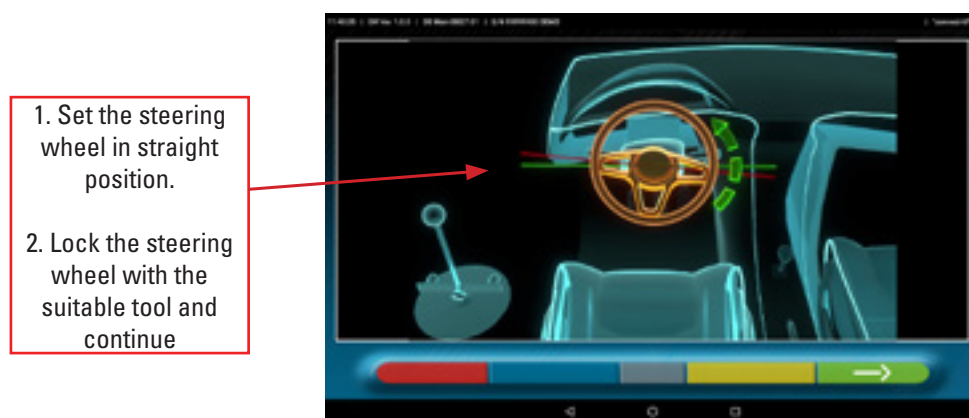
Press key to access the vehicle and customer data entry phase (See - Figure 61 on page 37)) from which it is possible to print (See par. 6.13 on page 37), share the measurements made (par. 6.14 on page 40) or, if necessary, save the tests (if TEq-Link is present See par. 6.15 on page 41).

Press key to display the chassis diagnosis page (par. 6.12.1 on page 36).

Press key to continue with the adjustment preliminary operations (par. 6.9 on page 32).

6.9 Adjustment preliminary operations

Selecting key from the diagnostic measures summary page (par. 6.8 on page 32), a page showing the adjustment preliminary operations will be displayed. Follow the instructions on the device to complete the adjustment preliminary operations:



- Figure 53 -

Press key to continue with the adjustment of the rear axle (par. 6.9 on page 32).

6.10 Adjusting the rear axle

The rear axle adjustment procedure can be accessed by pressing key  of - Figure 53, after having carried out the adjustment preliminary operations (par. 6.9 on page 32).

Adjust, where permitted, in the following order:

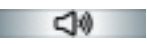
Rear inclination - Rear partial toe (this also determines the thrust angle).



- Figure 54 -

Press key  to perform the "Jack-Hold" procedure with the wheels raised (6.11.1 on page 35).
If there are adjustment help images (par. 6.2.3 on page 27), press key  to display them.

Press key  to continue the adjustment of the front (par. 6.11 on page 34).

NOTE: If you have configured the "adjustment by sound" function in the "  Application " menu (See Chap.5.1 on page 15 - Figure 13 on page 16),), click on the desired angle, the indication "  " will appear below it and a "Beep" will be emitted with a variable frequency based on the value itself.

Beep with very slow frequency > value out of tolerance

Beep with slow frequency > value close to tolerance

Beep with fast frequency > value within tolerance

Continuous beep > exact tolerance middle value

Click on the angle again to cancel the indication  and deactivate the "Beep".

6.11 Adjusting the front axle

The front axle adjustment procedure can be accessed by pressing key  on the rear axle adjustment page (- Figure 54) and after having carried out the adjustment preliminary operations (See par. 6.9 on page 32). The recommended order of the angles to be adjusted is as follows: CASTER - CAMBER - TOTAL TOE.

WARNING: The caster values, entering this phase, are “FROZEN” and displayed in grey.

To “UNFREEZE” the above mentioned values: press on the “Caster” values; the symbols “>” “<” appear and key  is displayed at the bottom; pressing on this key  will make the values become Red or Green (according to the tolerance) and the cursor “” will appear under the value.

Once the caster values have been adjusted, or even if they are not adjusted and deemed to be correct, it is advisable to “RE-FREEZE” the above values by pressing on the same key .

Then adjust the front axle



- Figure 55 -

Press key  to perform the “Jack-Hold” procedure with the wheels raised (6.11.1 on page 35)

If there are adjustment help images (par. 6.2.3 on page 27), press key  to display them.

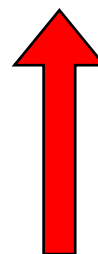
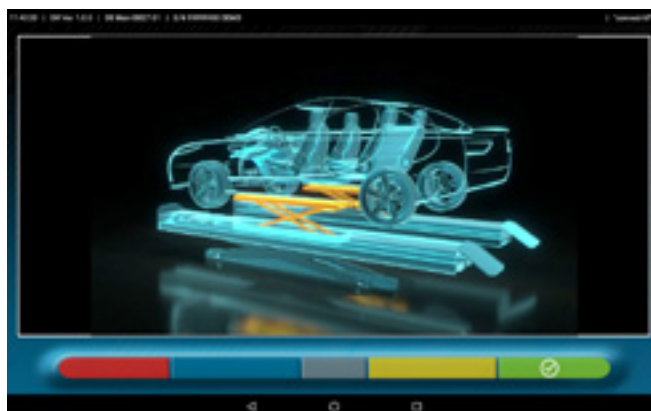
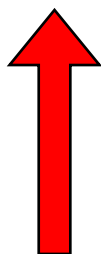
Press key  to continue to the summary of DIAGNOSIS and ADJUSTMENT data (par. 6.12 on page 36).

6.11.1 "Jack-Hold" procedure

From the measurement adjustment page (See - par. 6.10 e 6.11) press key  to perform the JACK-HOLD procedure.

Follow the visual instructions shown on screen.

Lift the vehicle



- Figure 56 -

When the vehicle is lifted press key  to confirm the lifting of the vehicle;
Now, with the vehicle lifted, it is possible to perform the adjustment.

Press key  to switch from the rear to the front adjustment and vice versa;

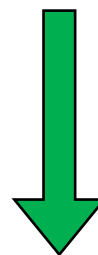
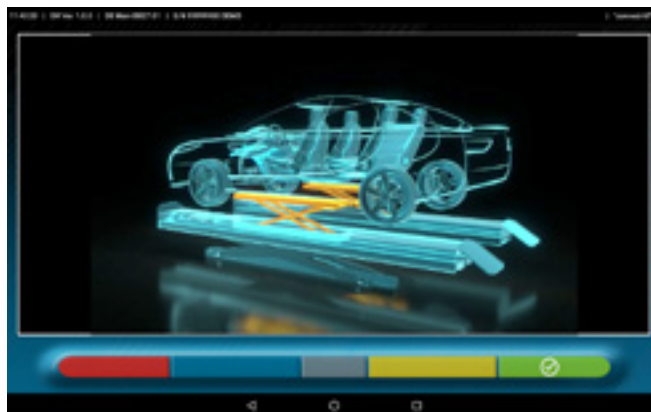
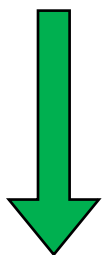


When the vehicle is raised, the icon  takes the following appearance

Press  to switch from rear to front and vice versa

- Figure 57 -

At the end of the adjustment, press key  to lower the vehicle and confirm with key  when it is correctly resting on the platforms.



- Figure 58 -

At this point of the adjustment, the program displays again - Figure 55 (See par. 6.11 on page 34) press key  to display the final summary (par. 6.12 on page 36)

6.12 Summary of DIAGNOSIS and ADJUSTMENT data

When the front adjustment phase on the vehicle has been completed (See - Figure 55 on page 34), after pressing key , the Diagnosis and Adjustment data summary page appears - Figure 59.



- Figure 59 -

Press key  to access the vehicle and customer data entry phase (See - Figure 61) from which it is possible to print or share the measurements taken (See par. 6.13 on page 37) and, if necessary, save the tests (if TEq-Link is present - See par. 6.14 on page 40).

By pressing key , the program goes back to the preliminary operations phase (par. 6.3 on page 28).

Note: if significant adjustments have been made, it is advisable to repeat the diagnosis phase starting from the preliminary operations in order to correctly recalculate the angle measurements.

Press key  to display the chassis diagnosis page (par. 6.12.1 on page 36).

Press key  to go back to the rear adjustment phase (par. 6.10 on page 33).

6.12.1 Chassis diagnosis

In the Diagnosis data summary page (par. 6.8) and in the Diagnosis and Adjustment summary page (par. 6.12) by pressing key , a page is shown with the graphic representation of the vehicle with the set-back measurements (axle toe-out) for the front and rear axles.



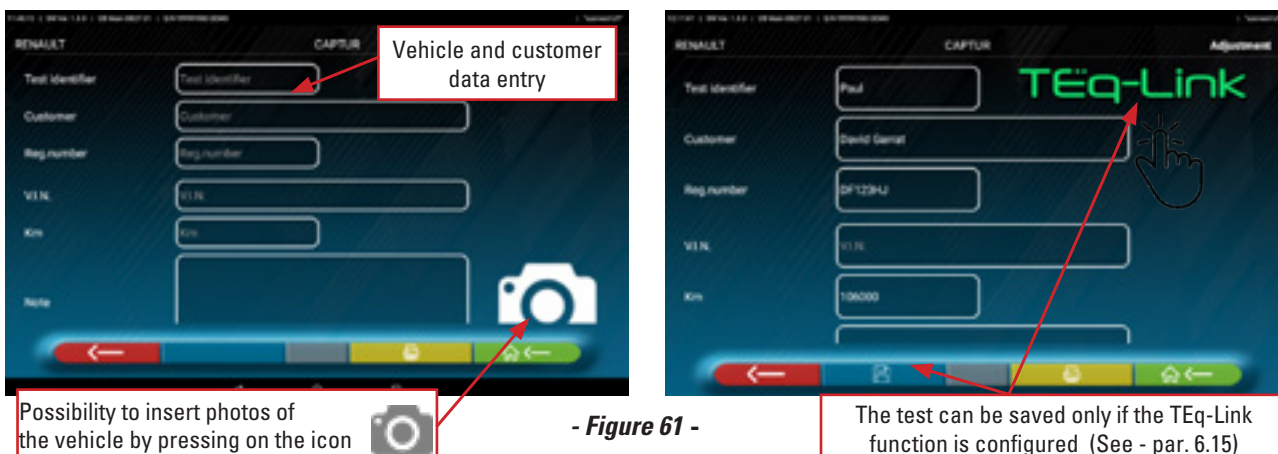
- Figure 60 -

This measurement is carried out during vehicle alignment phase (See par. 6.6 on page 30).

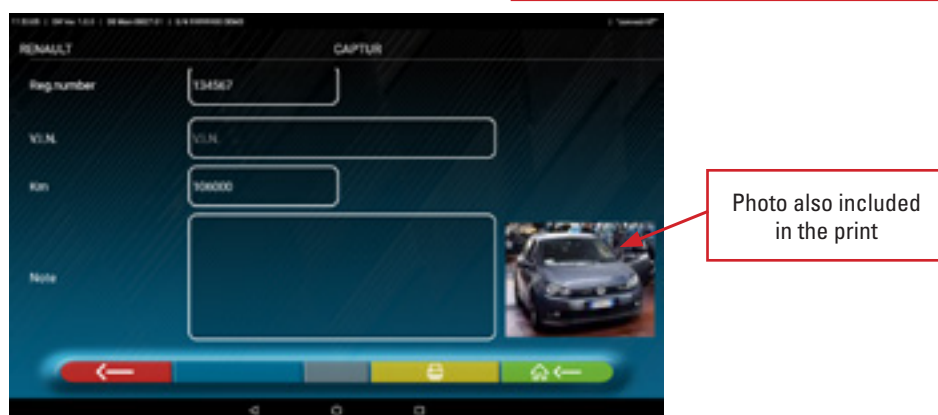
Press key  to quit and go back to the previous phase.

6.13 Printing the measurements made

Select key  on the test summary page (See 6.12 on page 36), to show the following screen, where you can enter vehicle and customer data:



- Figure 61 -



- Figure 62 -

Press key  if you want to go back to the front axle adjustment phase (par. 6.11 on page 34). Press key  to display the print preview of the test performed (See - Figure 63); the report is available in two formats (graphic or table- see examples on the following pages) configurable in the "PRINT" menu (See - Figure 59 on page 36); Press key  again to issue the report (*).



- Figure 63 -

Press key  from the page - Figure 62, to end the test and go back to the home page.

(*) The printer is not supplied with the CCD2.0WiFi system. You can still use generic Android or iOS compatible WiFi printers, and you can connect to the "connect" WiFi network of the Access Point provided (See - par. 4.5).

If you do not have a printer or TEq-Link function, you can save the .pdf file of the test locally and export it later.

6.13.1 Example of table printing

		Vehicle and customer data Date/time		Space reserved for workshop data customisation	
Customer	David Garrat	Date	25/11/2019 12:14	Km	106000
Reg.number	DF123HJ	VIN		Rim diam.	15"
Vehicle make	RENAULT	Chassis n.			
		Vehicle	CAPTUR		
SW Ver. 1.0.0	FL -- FR --				
FW	RL -- RR --				
Database	DB Main 0027.01				
Nominal values			Diagnosis		Adjustment
Total toe	lg	-0°20'	← →	← →	← →
Partial toe	lg	-0°10'	← →	← →	← →
Camber	lg	-1°14'	← →	← →	← →
Caster	lg	+4°00'	← →	← →	← →
King-pin	lg	+10°24'	← →	← →	← →
Incl. angle	lg	---	← →	← →	← →
Toe-out on turns	lg	---	← →	← →	← →
Steering in	lg	---	← →	← →	← →
Steering out	lg	---	← →	← →	← →
Total toe	lg	+0°02'	← →	← →	← →
Partial toe	lg	+0°02'	← →	← →	← →
Camber	lg	-1°10'	← →	← →	← →
Thrust angle	lg	-0°15'	← →	← →	← →

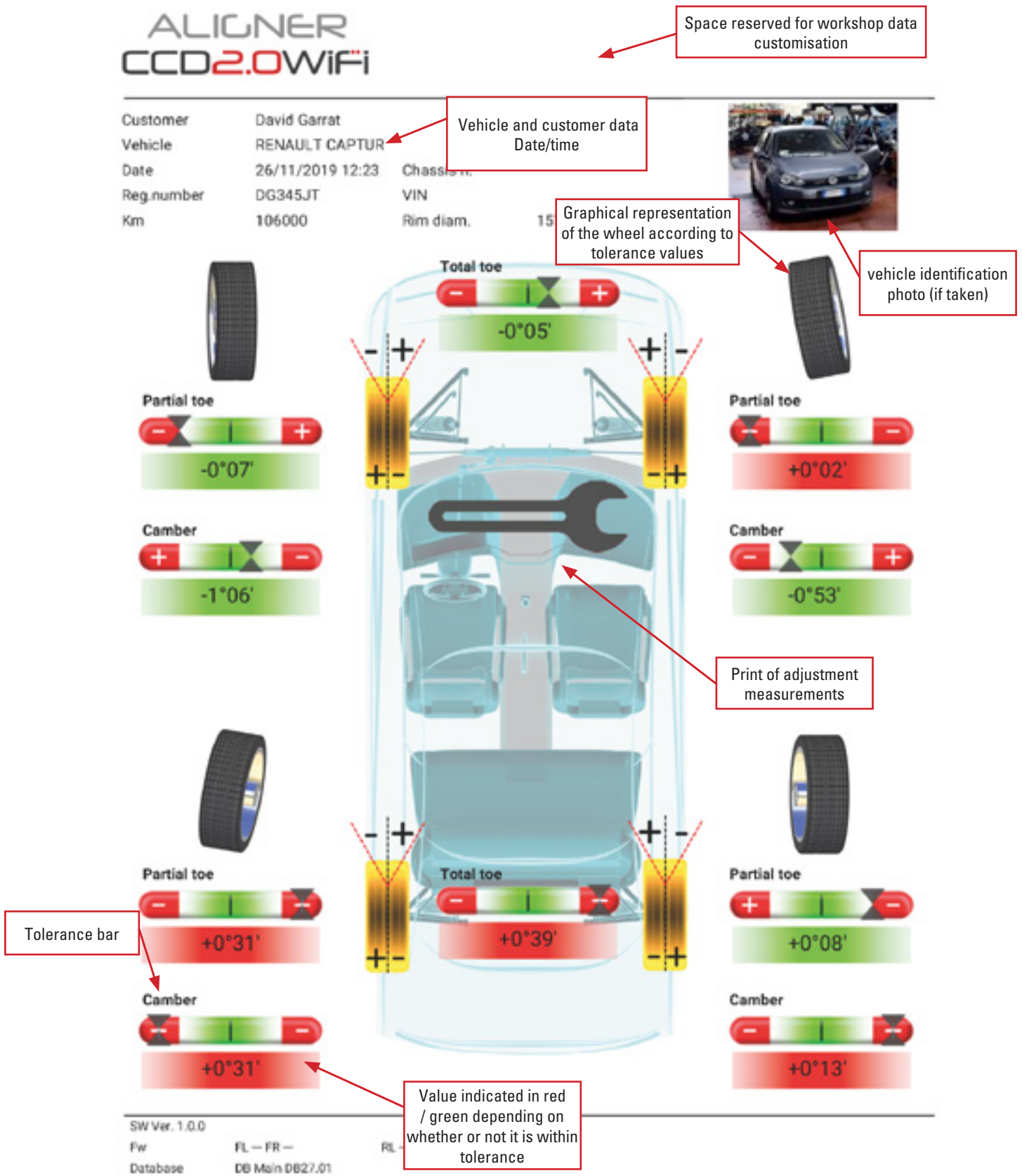
Total toe	lg	-0°15'	← →	← →	← →
Partial toe	lg	-1°06'	← →	← →	← →
Camber	lg	+0°17'	← →	← →	← →
Caster	lg	+4°23'	← →	← →	← →
King-pin	lg	+11°36'	← →	← →	← →
Incl. angle	lg	---	← →	← →	← →
Toe-out on turns	lg	---	← →	← →	← →
Steering in	lg	---	← →	← →	← →
Steering out	lg	---	← →	← →	← →
Total toe	lg	+0°39'	← →	← →	← →
Partial toe	lg	+0°31'	← →	← →	← →
Camber	lg	-0°30'	← →	← →	← →
Thrust angle	lg	-0°15'	← →	← →	← →

Total toe	lg	-0°05'	← →	← →	← →
Partial toe	lg	-0°07'	← →	← →	← →
Camber	lg	-1°06'	← →	← →	← →
Caster	lg	+0°17'	← →	← →	← →
King-pin	lg	+4°23'	← →	← →	← →
Incl. angle	lg	+3°17'	← →	← →	← →
Toe-out on turns	lg	---	← →	← →	← →
Steering in	lg	---	← →	← →	← →
Steering out	lg	---	← →	← →	← →
Total toe	lg	+0°39'	← →	← →	← →
Partial toe	lg	+0°31'	← →	← →	← →
Camber	lg	-0°31'	← →	← →	← →
Thrust angle	lg	+0°11'	← →	← →	← →



- Figure 64 -

6.13.2 Example of graphic printing



- Figure 65 -

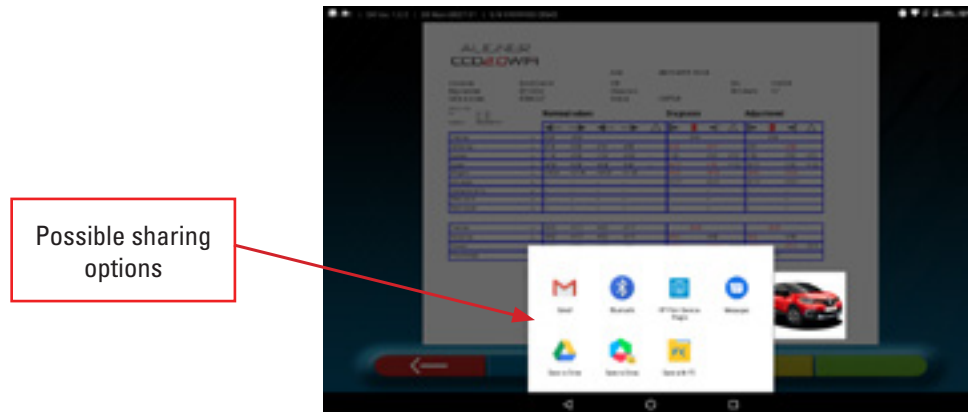
6.14 Sharing the test carried out

At the end of the test it is possible to share, for example via e-mail, the report with the results and all vehicle data.



Warning!: To share via E-Mail, the Tablet must have Internet access; for example, the WAN socket of the Access Point can be connected to a data structure with Internet access (See Chap. 4.5).

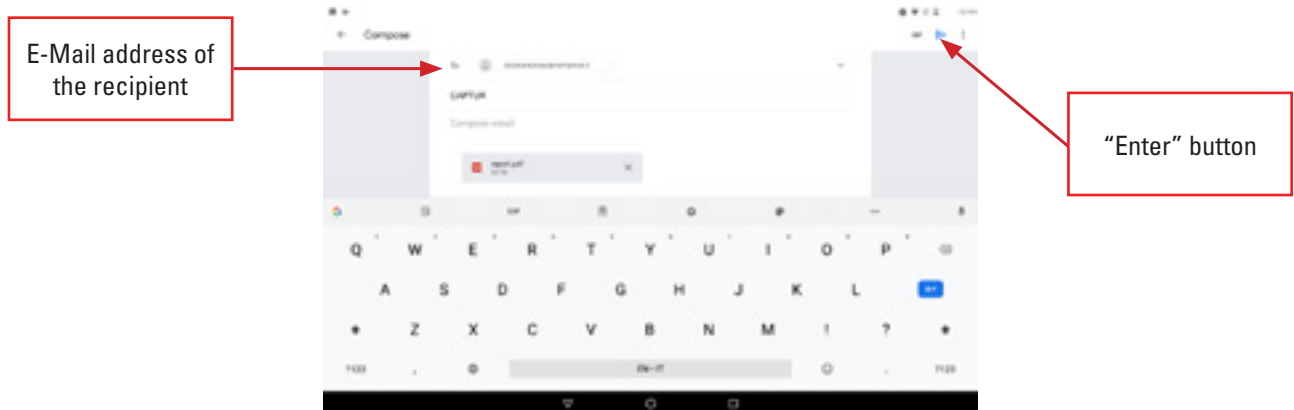
After previewing the print page (See - Figure 63), press key  window with the possible sharing options will appear (See - Figure 66).



- Figure 66 -

Select the sharing method; in this example  "E-MAIL"

Write the recipient's email address and press the "Send" button 



- Figure 67 -

The print report file is sent in .pdf format.

After sending the email, the print preview page (- Figure 63) is displayed again.

6.15 Saving the tests performed with TEq-Link

At the end of the test it is possible to save the report with the results and all the data related to the vehicle, through the function **TEq-Link**.

It is necessary to install the "TEq-Link Web Manager" software in a Personal Computer connected to the workshop computer network and connect the Tablet to the same data structure, for example by connecting the Access Point to a network socket shared with the PC where the "TEq-Link Web Manager" SW software is installed (See Chap. 3.5; see also references on the quick guide code M0335).



Warning! It is necessary to ask the manufacturer to enable the function in advance, communicating the serial number of your device (see information on the quick guide code M0335) and configure the App with the references of the PC where the software "TEq-Link Web Manager" is installed (See par. 6.15.1 on page 41).

After finishing the test, during the customer data entry phase (See - Figure 61 on page 37), you can save the test results using key

When the tests performed are stored, their results become immediately accessible from any PC or mobile device in the network shared with the Tablet.

6.15.1 Configuring the TEq-Link function

Before saving the test with TEq-Link function, you must first enter the references of the PC where the "TEq-Link Web Manager" software is installed.

Access from the configuration menu (See - par. 5.1)) to the "Application" settings and select the option **TEq-Link**

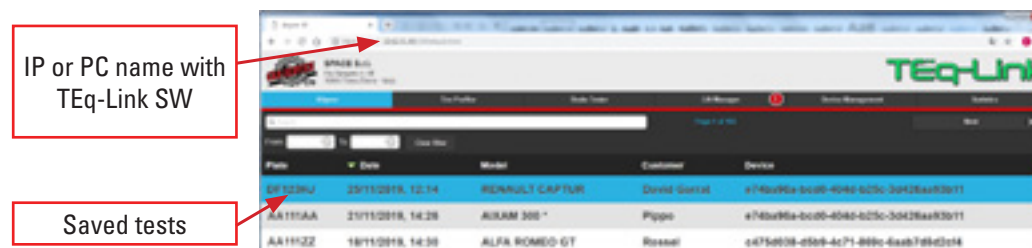
Then enter the IP address of the PC where the "TEq-Link Web Manager" software is installed, or enter the name of the PC it self See - Figure 68.



Enter the I.P. Address or PC name with the SW "TEqLink Web Manager"

- Figure 68 -

From any PC or mobile device in the same network, by simply entering the I.P. or the name of the PC with the SW "TEqLink Web Manager", in the address bar of the browser you can access the main page for the management of saved tests; see example in - Figure 69.



IP or PC name with TEq-Link SW

Saved tests

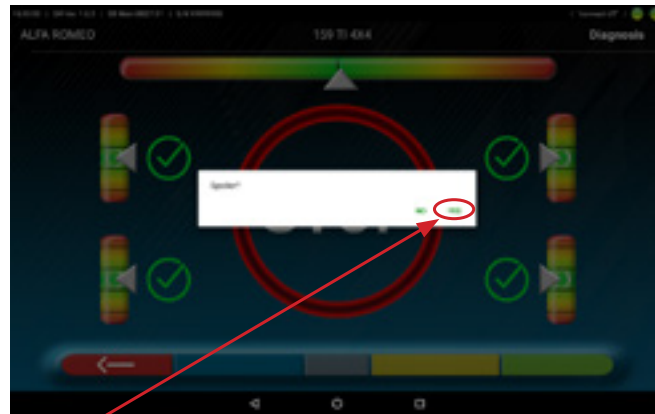
- Figure 69 -

Note: the same page also opens on the Tablet by clicking on key on the application's home page (See - Figure 29).

7 FRONT AXLE SPOILER PROCEDURE

During alignment and levelling operations on sensors (See par. 6.6 on page 30), it could happen that a vehicle, equipped with a front spoiler, prevents front sensors from taking the measurement with the alignment transducers at the end of the arm (See - Figure 6 on page 12).

If the measurement is prevented, the problem is automatically detected and managed by the program, which shows the following screen:



- Figure 70 -

Press YES to start the Spoiler procedure (See - Figure 70).

Attention: Sometimes the Spoiler procedure can be required even when there is no obstacle between front sensors, but the latter still cannot take any measurement because values are outside the maximum range of $\pm 2.50^\circ$.
E.g.: the vehicle is crashed and no pre-adjustment was performed.
In this case, it is possible to display a page showing the alignment angles by pressing key .



- Figure 71 -

In this case, adjust the front alignment values possibly to around 0° . After having obtained valid values ($<2.5^\circ$), press key  to repeat the alignment step (see chap. 5.7); the spoiler procedure will not be necessary if the program moves on to the next step (See - Chap. 6.7).



A graphic representation of the procedure is shown (- Figure 72): The arrow indicates that the front left sensor must be unlocked and lowered as much as necessary for the transducer at the end of the arm to be below the spoiler. Brake the sensor again. The central key of the sensor keypad displayed on screen will start flashing to indicate that it must be pressed on the concerned sensor to continue the procedure.



- Figure 72 -

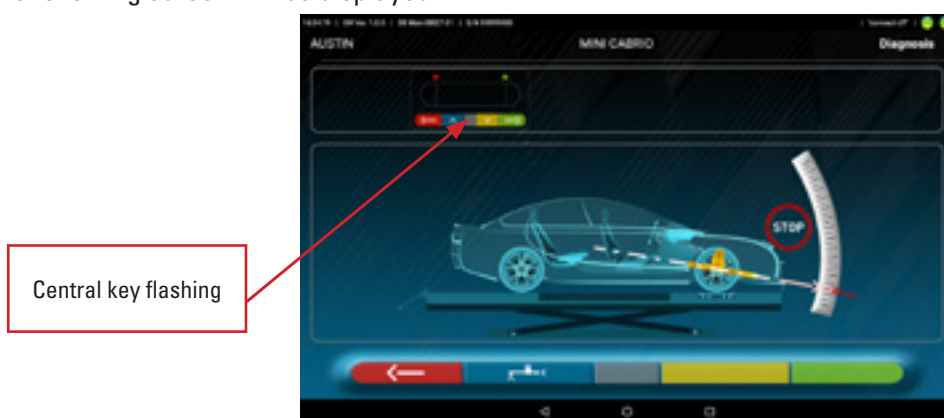
The following screen is displayed when the key is pressed:



- Figure 73 -

At this point, the front right sensor must be unlocked, lowered, until the level indicator is perfectly aligned with the target point, and then locked again.

The following screen will be displayed:



- Figure 74 -

In - Figure 74 - the central key of the sensor keypad flashes to indicate that it must be pressed again to

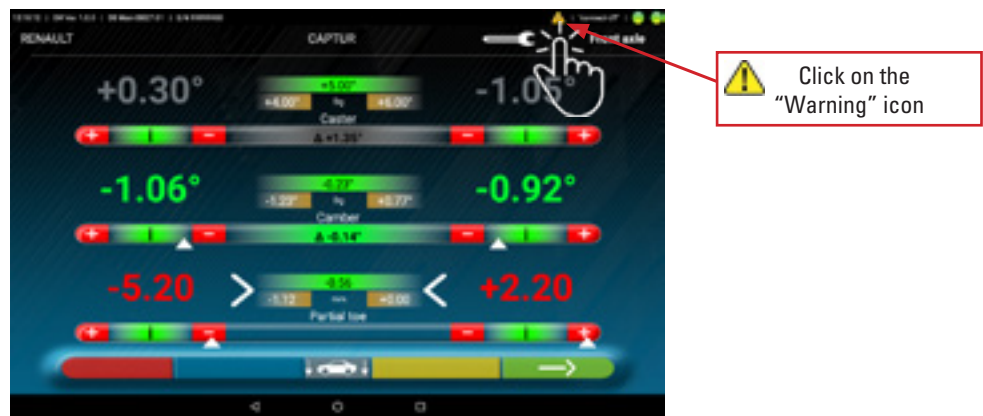
continue the procedure. By pressing the central key, the symbol  remains displayed for a few seconds at the centre of the page, during the acquisition of the angle measurement.

Then, after the acquisition, the screen showing alignment and levelling operations on sensors will appear again (See par. 6.6 on page 30):

It will be necessary to level the front sensors again; since it is no longer necessary to perform the measurement with the alignment transducers on the end of the arm (it is acquired with the Spoiler program) the program automatically moves to the next step (steering procedure See par. 6.7 on page 31).

8 ERROR SIGNALLING

During data transmission/reception between sensors and Tablet, or during angle measurement (e.g. during adjustment) a “Warning” symbol “” may appear to indicate an error condition; See - Figure 75. Click on the “Warning” icon to view the detail of the error detected



- Figure 75 -

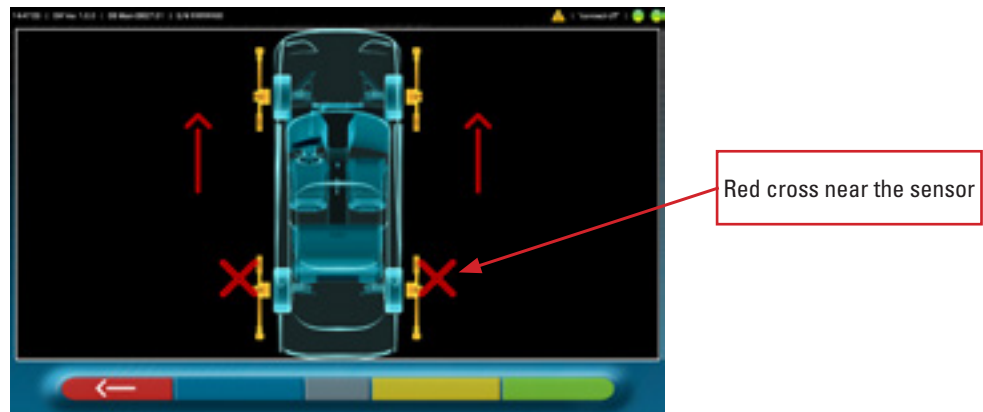
Two types of errors can be highlighted :

Errors of data transmission/reception between sensors -See chap. 8.1

Angle measurement errors in the horizontal plane -See Chap. 8.2

In addition, it is possible that a “low battery” condition is signalled - See Chap. 3.6.3

8.1 Data transmission error between sensors



- Figure 76 -

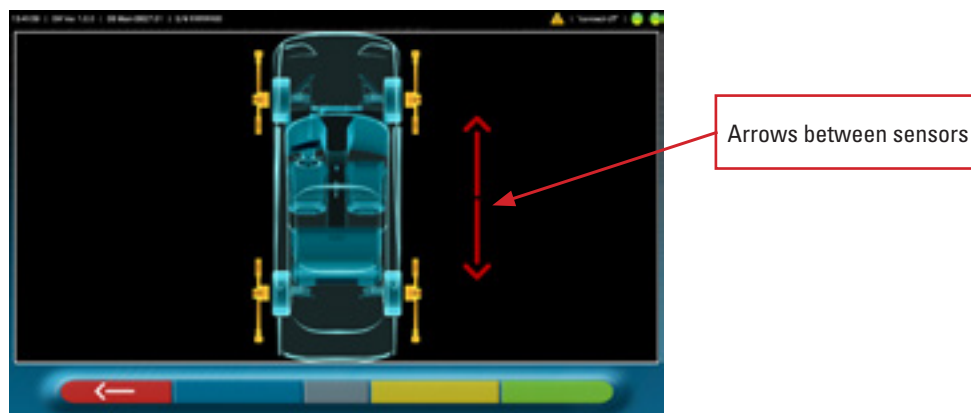
This indicates that there is a transmission/reception failure due to one or more of the following problems:

- The infrared transceivers on the sensors are not working.
- There is a fault or interference in the transmission system.
- There is an obstacle (e.g. open vehicle door) between the front and rear sensors.

Note: The rear sensors do not communicate directly with the tablet: their data are transmitted/received through the front sensors, so in case a front sensor is not working properly, it would be impossible to transmit the data of the corresponding rear sensor, even if it was working.

If you remove the cause of the malfunction (i.e, the vehicle door is closed) the error page disappears immediately and the measurement page appears again on the tablet. If the problem persists it is necessary to check the hardware by contacting the technical support service.

8.2 Angle measurement error in the horizontal plane



- Figure 77 -

This error page indicates that one or more infrared measurements in the horizontal plane cannot be made.

Possible causes include:

- One or more CCD sensors (digital transducer for measuring angles in the horizontal plane) do not work.
- One or more infrared light emitters for measuring angles in the horizontal plane do not work (I.R. LED).
- There is an obstacle between the front and rear sensors.

If you remove the cause of the malfunction, the error page disappears immediately and the measurement page appears again on the monitor. If the problem persists it is necessary to check the hardware by contacting the technical support service.

9 PROBLEMS



Some possible problems of wheel alignment equipment are listed below.

The Manufacturer declines all responsibility for problems due to animals and things, for the intervention of unauthorized personnel and for the use of non-original spare parts.

Before performing any work on the system, the power supply must be switched off.

In case of doubt do not interpret, please contact technical assistance in advance in order to receive instructions on how to carry out operations in conditions of maximum safety.

INCONVENIENT	CAUSE	SOLUTION
Sensors do not turn on	- Battery fully discharged	- Recharge battery
Sensors are not recharged on the stands	- Mains power failure - Protection fuses interrupted	- Check mains voltage - Check protection fuses
Sensors do not communicate with the Tablet	- Mains power failure - Protection fuses interrupted - Router disconnected from the network - Tablet not connected to the WiFi network	- Check mains voltage - Check protection fuses - Connect Router to the network - Connect the tablet to the Wi-Fi network

10 MAINTENANCE



WARNING! Before carrying out any maintenance work it is necessary to disconnect the machine from the mains by switching off the general power supply.

To clean plastic panels or shelves use neutral detergents (AVOID LIQUIDS CONTAINING SOLVENTS IN ANY CASE).

The sensors can be cleaned with a damp cloth, then dried. Do not spray liquids directly onto the sensors and avoid cleaning with strong jets of compressed air.

Keep the filters clean using a freshly damp cloth, do not use solvents;

Cleaning and other Tablet maintenance operations are described in the manual supplied with the Tablet. Always refer to the latter before performing any maintenance work on the Tablet.

11 DECOMMISSIONING AND SCRAPPING



Decommissioning - In the event of long-term decommissioning, it is necessary to disconnect the power sources and batteries of the sensors and provide for the protection of the sensor optical units that could deteriorate due to excessive dust deposit.

Scrapping - When you decide to stop using this equipment, it is recommended to make it inoperative:

It is recommended to make sure that parts that could pose risks are made harmless. Evaluate the classification of the good according to the degree of disposal.

Scrap as scrap iron and deliver in designated collection centres.

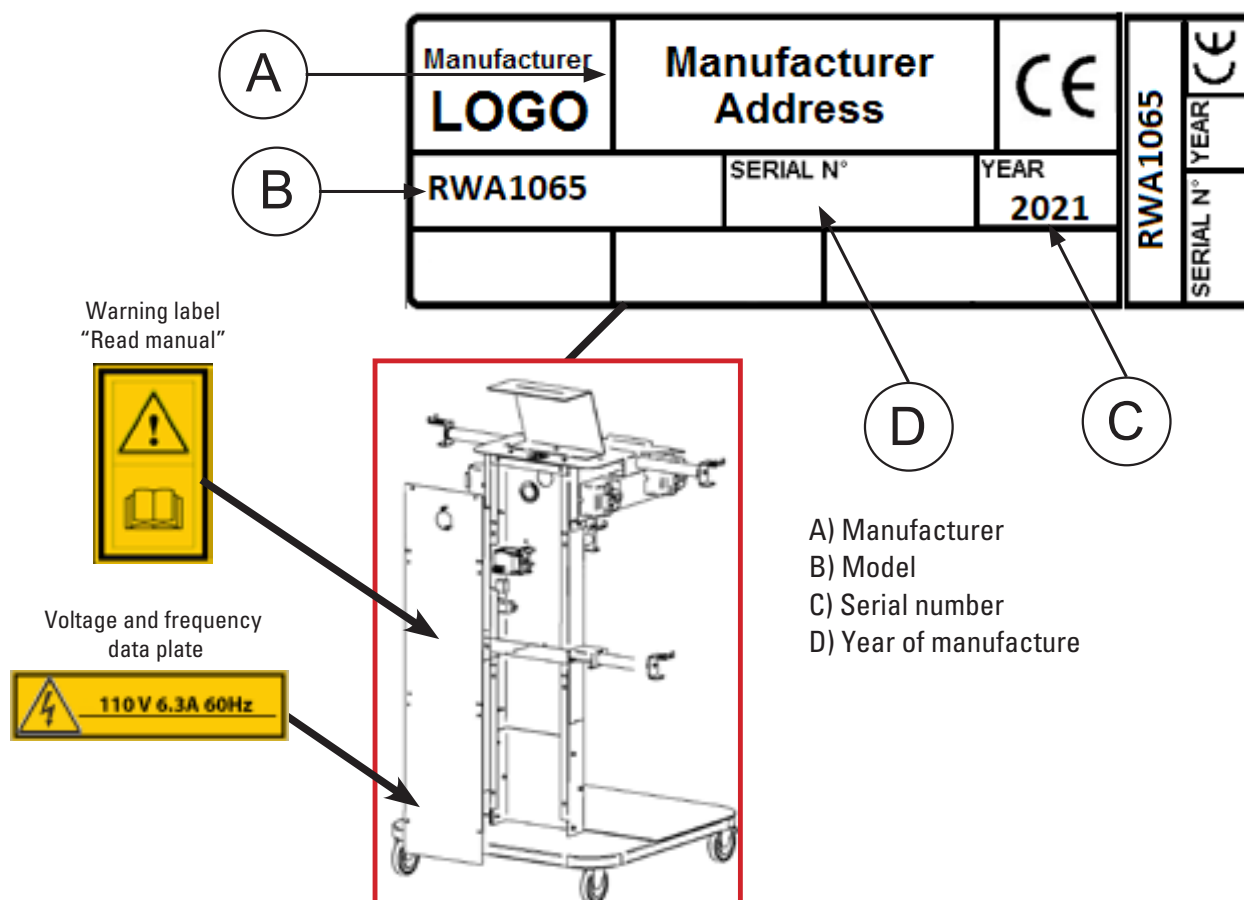
If considered special waste, disassemble and divide into homogeneous parts, then dispose of according to the laws in force.



In order to inform users on how to dispose of batteries and accumulators correctly, the following shall be communicated: The meaning of the crossed-out wheeled bin symbol on the accumulator indicates that the product must not be thrown in undifferentiated rubbish (i.e. together with "mixed municipal waste"), but must be handled separately, in order to be subjected to appropriate operations for its reuse or treatment, to remove

and safely dispose of any substances that are hazardous to the environment and extract and recycle raw materials that can be reused. For more detailed information on the end-of-life management of batteries and accumulators, please consult the After-sales Service.

12 MACHINE IDENTIFICATION DATA



WARNING: It is absolutely forbidden to tamper with, engrave, alter in any way or even remove the identification plates of the machine; do not cover with temporary panels etc. as they must always be clearly visible.

Always keep these plates clean of grease or dirt in general.

WARNING: If for accidental reasons the identification plates are damaged (detached from the machine, damaged or even partially illegible), notify the manufacturer immediately.

Installer: Please return this booklet to literature package, and give to wheel aligner owner/operator.

Thank You

Trained Operators and Regular Maintenance Ensures Satisfactory Performance of Your Wheel Service Equipment.

Contact Your Nearest Authorized Rotary Wheel Service Equipment Parts Distributor for Genuine Replacement Parts. See Literature Package for Parts Breakdown.

Rotary World Headquarters
2700 Lanier Drive
Madison, IN 47250, USA
www.rotarylif.com

North America Contact Information

Tech. Support:
p 800.445.5438
f 800.578.5438
e userlink@rotarylif.com
Sales: p 800.640.5438
f 800.578.5438
e userlink@rotarylif.com

World Wide Contact Information

World Headquarters/USA: 1.812.273.1622
Canada: 1.905.812.9920
European Headquarters/Germany: +49.771.9233.0
United Kingdom: +44.178.747.7711
Australasia: +60.3.7660.0285
Latin America / Caribbean: +54.3488.431.608
Middle East / Northern Africa: +49.771.9233.0

© Vehicle Service GroupSM

Printed in U.S.A., All Rights Reserved. Unless otherwise indicated, ROTARY, and all other trademarks are property of Dover Corporation and its affiliates.

